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ABSTRACT. The study of Gaussian measures on Banach spaces is of active interest both in pure and applied mathematics. In particular, the spectral theorem for self-adjoint compact operators on Hilbert spaces provides a canonical decomposition of Gaussian measures on Hilbert spaces, the so-called Karhunen-Loève expansion. In this paper, we extend this result to Gaussian measures on Banach spaces in a very similar and constructive manner. In some sense, this can also be seen as a generalization of the spectral theorem for covariance operators associated to Gaussian measures on Banach spaces. In the special case of the standard Wiener measure, this decomposition matches with Paul Lévy's construction of Brownian motion.

1. PRELIMINARIES ON GAUSSIAN MEASURES

Let us first remind a few properties of Gaussian measures on Banach spaces. Our terminology and notations are essentially taken from [2] (alternative presentations can be found in [7], [15] or [5]). In this work, we consider a separable Banach space X, equipped with its Borel σ-algebra $\mathcal{B}(X)$. Note that every probability measure on $(X, \mathcal{B}(X))$ is Radon and that Borel and cylindrical σ-algebras are equal in this setting.

A probability measure γ on $(X, \mathcal{B}(X))$ is Gaussian if and only if for all $f \in X^*$ (the topological dual space of X), the pushforward measure $\gamma \circ f^{-1}$ (of γ through f) is a Gaussian measure on $(\mathbb{R}, \mathcal{B}(\mathbb{R}))$. Here, we only consider the case γ centered for simplicity (the general case being obtained through a translation). An important tool in the study of a (Gaussian) measure is its characteristic functional $\hat{\gamma}$ (or Fourier transform)

$$\hat{\gamma} : f \in X^* \to \hat{\gamma}(f) = \int_X e^{i\langle x,f \rangle_{X,X^*}} \gamma(dx) \in \mathbb{C},$$

where $\langle .,. \rangle_{X,X^*}$ is the duality pairing. Since γ is a centered Gaussian measure, we have

$$(1.1) \qquad \forall f \in X^*, \ \hat{\gamma}(f) = \exp\left(-\frac{C_\gamma(f,f)}{2}\right),$$

where C_γ is the covariance function

$$C_\gamma : (f,g) \in X^* \times X^* \to \int_X \langle x,f \rangle_{X,X^*} \langle x,g \rangle_{X,X^*} \gamma(dx) \in \mathbb{R}.$$

One of the most striking results concerns integrability. Indeed, using a rotation invariance principle, it has been shown that a Gaussian measure γ admits moments (in a Bochner sense) of all orders (as a simple corollary of Fernique's theorem, see [2]). Consequently, its covariance operator may be defined as

$$R_\gamma : f \in X^* \to \int_X \langle x,f \rangle_{X,X^*} x\gamma(dx) \in X,$$

using Bochner's integral and is characterized by the following relation

(1.2) $$\forall (f,g) \in X^* \times X^*, \ \langle R_\gamma f, g \rangle_{X,X^*} = C_\gamma(f,g).$$

Most noticeably, R_γ is a symmetric non-negative kernel:

$$\begin{aligned} \forall (f,g) \in X^* \times X^*, \ \langle R_\gamma f, g \rangle_{X,X^*} &= \ \langle R_\gamma g, f \rangle_{X,X^*}, \\ \forall f \in X^*, \ \langle R_\gamma f, f \rangle_{X,X^*} &\geq \ 0. \end{aligned}$$

Furthermore, the Cameron-Martin space $H(\gamma)$ associated to γ is the Hilbertian subspace of X with reproducing kernel R_γ (see [12] and [1] for the usual case of reproducing kernel Hilbert spaces). In particular, we will extensively use the so-called *reproducing property*

$$\forall h \in H(\gamma), \ \forall f \in X^*, \ \langle h,f \rangle_{X,X^*} = \langle h, R_\gamma f \rangle_\gamma,$$

where $< .,. >_\gamma$ denotes the inner product of $H(\gamma)$. Note that $H(\gamma)$ is continuously embedded in X and admits $R_\gamma(X^*)$ as a dense subset. Additionally, the covariance operator has been shown to be nuclear and in particular compact (see [15], Chapter 3 for a detailed presentation and proofs).

Our objective is to decompose Gaussian measures which, in fact, can be done by considering any Hilbert basis of the Cameron-Martin space. Indeed, let $(h_n)_n$ be an arbitrary orthonormal basis of $H(\gamma)$ and $(\xi_n)_n$ a sequence of independent standard Gaussian random variables defined on a probability space $(\Omega, \mathcal{F}, \mathbb{P})$. Then the series

$$\sum_n \xi_n(\omega) h_n,$$

converges almost surely in X and the distribution of its sum is the Gaussian measure γ (cf. theorem 3.5.1 p. 112 in [2]). More precisely, we will construct a sequence $(h_n^*)_n$ in X^* such that $\forall n \in \mathbb{N}, \ h_n = R_\gamma h_n^*$. Hence, the corresponding decomposition in X (for the strong topology) will be

$$x = \sum_n \langle x, h_n^* \rangle_{X,X^*} h_n,$$

γ almost everywhere, where $(h_n^*)_n$ is a sequence of independent standard normal random variables. Roughly speaking, it means that γ can be seen as the countable product of the standard normal distribution $N(0,1)$ on the real line:

$$\gamma = \bigotimes_n N(0,1).$$

For a recent review of the interplay between covariance operators and Gaussian measures decomposition, consult [8]. To see how to construct such a basis, we start with the Hilbert case.

2. Gaussian measures on Hilbert spaces

Hilbert geometry has nice features that are well understood, including Gaussian measures structure (see [7] and [3] for a recent treatment). First of all, Riesz representation theorem allows to identify X^* with X. As a linear operator on a Hilbert space, the covariance operator R_γ of a Gaussian measure γ is self-adjoint and compact. Spectral theory exhibits a particular Hilbert basis of X given by the set $(x_n)_n$ of eigenvectors of R_γ. Using this specific basis, the covariance operator is

$$R_\gamma : x \in X \to \sum_n \lambda_n \langle x, x_n \rangle_X x_n \in X,$$

where $\langle .,. \rangle_X$ is the inner product of X. A simple normalization, namely $h_n = \sqrt{\lambda_n} x_n$, provides a Hilbert basis of $H(\gamma)$. The nuclear property of R_γ simplifies to

$$\sum_n \|h_n\|_X^2 = \sum_n \lambda_n < +\infty.$$

Using the terminology of random elements, let Y be the infinite-dimensional vector defined almost surely by

$$Y(\omega) = \sum_n \xi_n(\omega) h_n = \sum_n \sqrt{\lambda_n} \xi_n(\omega) x_n,$$

where $(\xi_n)_n$ is a sequence of independent standard normal random variables. Then γ is the distribution of the Gaussian vector Y. In the context of stochastic processes, this representation is well-known as the Karhunen-Loève expansion ([6], [9]) of the process $Y = (Y_t)_{t \in T}$ (assumed to be square-integrable over a closed and bounded interval T).

In order to extend this spectral decomposition to the Banach case, let us recall the following simple property (where B_X denotes the unit closed ball of X):

$$(2.1) \qquad \lambda_0 = \sup_{x \in X \setminus \{0\}} \frac{\langle R_\gamma x, x \rangle_X}{\|x\|_X^2} = \max_{x \in B_X} \langle R_\gamma x, x \rangle_X$$

is the largest eigenvalue of R_γ and is equal to the Rayleigh quotient $\frac{\langle R_\gamma x_0, x_0 \rangle_X}{\|x_0\|_X^2}$ where x_0 is any corresponding eigenvector. A similar interpretation is valid for every $n \in \mathbb{N}$:

$$\lambda_n = \max_{x \in B_X \cap span(x_0,\ldots,x_{n-1})^\perp} \langle R_\gamma x, x \rangle_X.$$

Keeping this interpretation in mind, we can now consider the Banach case.

3. Gaussian measures in Banach spaces

In the context of Banach spaces, the previous spectral decomposition of the covariance operator doesn't make sense anymore. Nevertheless, we will show in section 3.1 that the Rayleigh quotient is well defined in this context (lemma 3.1). Combining this and a simple decomposition method (lemma 3.2), we give in section 3.2 an iterative decomposition scheme of a Gaussian measure. Main analysis and results are given in the last section 3.3.

3.1. **Rayleigh quotient and split decomposition.** The first lemma in this section is an existence result of particular linear functionals based on a compactness property. The second one provides a method to separate a Banach space into two components with respect to a linear functional and a Gaussian measure. These results are given independently to emphasize that lemma 3.2 could be combined with different linear functionals to define other iterative decomposition schemes (see section 3.2).

Lemma 3.1. *Let γ be a Gaussian measure on $(X, \mathcal{B}(X))$ a separable Banach space and set $\lambda_0 = \sup_{f \in B_{X^*}} \langle R_\gamma f, f \rangle_{X,X^*} \in [0, +\infty]$. Then*

$$\exists f_0 \in B_{X^*}, \ \lambda_0 = \langle R_\gamma f_0, f_0 \rangle_{X,X^*}.$$

Moreover, we may assume $\|f_0\|_{X^*} = 1$.

Proof of lemma 3.1. Let $(f_n)_n \in B_{X^*}$ be a maximizing sequence:

$$\langle R_\gamma f_n, f_n \rangle_{X,X^*} \to \lambda_0 \in [0, +\infty].$$

From the weak-star compactness of B_{X^*} (see Banach-Alaoglu theorem), we can suppose that $f_n \rightharpoonup f_\infty$ for the $\sigma(X^*, X)$-topology where $f_\infty \in B_{X^*}$. This implies that

$$\hat{\gamma}(f_n) = \int_X e^{i\langle x, f_n \rangle_{X,X^*}} \gamma(dx) \to \int_X e^{i\langle x, f_\infty \rangle_{X,X^*}} \gamma(dx) = \hat{\gamma}(f_\infty),$$

using Lebesgue's convergence theorem. From equations 1.1 and 1.2, we conclude that $\langle R_\gamma f_n, f_n \rangle_{X,X^*} \to \langle R_\gamma f_\infty, f_\infty \rangle_{X,X^*}$. Hence $\lambda_0 = \langle R_\gamma f_\infty, f_\infty \rangle_{X,X^*} \in \mathbb{R}_+$. If $\lambda_0 > 0$, then $\|f_\infty\|_{X^*} = 1$ and we can take $f_0 = f_\infty$. In the degenerate case $\lambda_0 = 0$, we have $R_\gamma = 0$ and any f_0 of unit norm is appropriate. $\square$

We will now show how to split both X and γ, given any $f \in X^*$ of non trivial Rayleigh quotient (in the previous sense).

Lemma 3.2. *Let $\gamma \neq \delta_0$ be a non trivial Gaussian measure on a separable Banach space $(X, \mathcal{B}(X))$. Pick $f_0 \in X^*$ such that $\|f_0\|_{X^*} = 1$ and $\lambda_0 = \langle R_\gamma f_0, f_0 \rangle_{X,X^*} > 0$. Set $P_0 : x \in X \to \langle x, f_0 \rangle_{X,X^*} x_0$, $R_\gamma f_0 = \lambda_0 x_0$ and $h_0 = \sqrt{\lambda_0} x_0$, then we have the following properties.*

(1) $\langle x_0, f_0 \rangle_{X,X^*} = 1$ *and* $\|h_0\|_\gamma = 1$.
(2) P_0 *is the projection on X with range $\mathbb{R}x_0$ and null space $\ker(f_0) = \{x \in X, \langle x, f_0 \rangle_{X,X^*} = 0\}$. Furthermore, the restriction Q_0 of P_0 on $H(\gamma)$ is the orthogonal projection onto $\mathbb{R}h_0$:*

$$h \in H(\gamma), \ \langle h, f_0 \rangle_{X,X^*} x_0 = \langle h, h_0 \rangle_\gamma h_0.$$

(3) *According to the decomposition $x = P_0 x + (I - P_0)x$ in X, the Gaussian measure γ can be decomposed as*

$$\gamma = \gamma_{\lambda_0} * \gamma_1,$$

where $\gamma_{\lambda_0} = \gamma \circ P_0^{-1}$ and $\gamma_1 = \gamma_0 \circ (I - P_0)^{-1}$ are Gaussian measures with respective covariance operators:

$$\begin{aligned} R_{\lambda_0} : f \in X^* &\to \ \lambda_0 \langle x_0, f \rangle_{X,X^*} x_0, \\ R_{\gamma_1} : f \in X^* &\to \ R_\gamma f - R_{\lambda_0} f. \end{aligned}$$

In particular,

$$R_\gamma f = \lambda_0 \langle x_0, f \rangle_{X,X^*} x_0 + R_{\gamma_1} f.$$

(4) *The Cameron-Martin space $H(\gamma)$ is decomposed as*

$$H(\gamma) = \mathbb{R}h_0 \oplus H(\gamma_1),$$

where $H(\gamma_1) = (I - Q_0)(H(\gamma)) = (\mathbb{R}h_0)^\perp$ equipped with the inner product of $H(\gamma)$ is the Cameron-Martin space of γ_1.

(5) *For each $t \in \mathbb{R}$, denote by $tx_0 + \gamma_1$ the Gaussian measure on X centered at tx_0 with covariance operator R_{γ_1}. Then, γ^t is the conditional probability distribution of $x \in X$ given $f_0(x) = t$:*

$$\forall B \in \mathcal{B}(X),\ \gamma^t(B) = \gamma_1(B - tx_0) = \gamma(B|f_0 = t).$$

Moreover, f_0 is $\mathcal{N}(0, \lambda_0)$ and the deconditioning formula is as follows:

$$\gamma(B) = \int_{\mathbb{R}} \gamma^t(B) \frac{e^{-\frac{t^2}{2\lambda_0}}}{\sqrt{2\pi\lambda_0}} dt.$$

The proof is straightforward and is given in the appendix. Concerning the last property on conditioning, it is worth noting that the conditional covariance operator R_{γ_1} does not depend of the particular value t of the random variable $f_0 \in X^*$. We will now use both of these lemmas to build a complete decomposition of any Gaussian measure γ.

3.2. **Iterative decomposition of a Gaussian measure.** Consider a (centered) Gaussian measure γ on a separable Banach space $(X, \mathcal{B}(X))$. The initial step of the decomposition is to split X and γ according to lemma 3.2 using $f_0 \in X^*$ given by lemma 3.1. The same process is applied to the *residual* Gaussian measure γ_1 defined in lemma 3.2, and so on and so forth. Now, we formalize the resulting iterative decomposition scheme.

Define $\gamma_0 = \gamma$ (initialization). By induction on $n \in \mathbb{N}$ (iteration), we define the Gaussian measure γ_{n+1} of covariance operator $R_{\gamma_{n+1}}$ such that

$$\forall f \in X^*,\ R_\gamma f = \sum_{k=0}^n \lambda_k \langle x_k, f \rangle_{X,X^*} x_k + R_{\gamma_{n+1}} f$$

where $\lambda_n = \max_{f \in B_{X^*}} \langle R_{\gamma_n} f, f \rangle_{X,X^*}$ and where x_n is defined by the relation $R_{\gamma_n} f_n = \lambda_n x_n$ with f_n chosen such that $\lambda_n = \langle R_{\gamma_n} f_n, f_n \rangle_{X,X^*}$.

From lemma 3.2, we have the orthogonal decomposition for all n

$$H(\gamma) = span(h_0, ..., h_n) \oplus H(\gamma_{n+1})$$

where $h_n = \sqrt{\lambda_n} x_n$. If for some n, $\lambda_{n+1} = 0$, then $R_{\gamma_{n+1}} = 0$ and $H(\gamma_{n+1}) = \{0\}$, which means that R_γ is a finite-rank operator and $H(\gamma) = span(h_0, ..., h_n) = span(x_0, ..., x_n)$ a finite-dimensional linear space. This means that γ is a finite-dimensional Gaussian measure with support equal to its Cameron-Martin space. Theorem 3.3 gives the properties of this decomposition in the general case where $H(\gamma)$ is infinite-dimensional.

Theorem 3.3. *Suppose $H(\gamma)$ is infinite-dimensional and keep previous notations, we have the following properties.*

(1) *$(h_n)_n$ is an orthonormal sequence in $H(\gamma)$.*

(2) *$(x_n)_n$ and $(f_n)_n$ are satisfying the following relations:*

(a) $\forall n \in \mathbb{N}$, $\|x_n\|_X = \langle x_n, f_n \rangle_{X,X^*} = 1$,

(b) $\forall (k,l) \in \mathbb{N}^2$, $k > l$, $\langle x_k, f_l \rangle_{X,X^*} = 0$.

(3) *Let $Q_n : h \in H(\gamma) \to Q_n h = \sum_{k=0}^n \langle h, h_k \rangle_\gamma h_k$ be the orthogonal projection onto the linear space $span(h_0, ..., h_n) = span(x_0, ..., x_n)$ in $H(\gamma)$. Then, we have $Q_n h = \sum_{k=0}^n \langle h - Q_{k-1} h, f_k \rangle_{X,X^*} x_k$, with the convention that $Q_{-1} = 0$.*

(4) *Define P_n on X by $P_n x = \sum_{k=0}^n \langle x - P_{k-1} x, f_k \rangle_{X,X^*} x_k$, with the same convention $P_{-1} = 0$. Then, P_n is the projection onto $span(x_0, ..., x_n)$ and null space $\{x \in X : \langle x, f_k \rangle_{X,X^*} = 0 \text{ for } k = 0, ..., n\}$. Furthermore, the operator P_n restricted to $H(\gamma)$ is equal to Q_n.*

(5) *According to the decomposition $x = P_n x + (I - P_n)x$ in X, the Gaussian measure γ can be decomposed as $\gamma = \gamma_{\lambda_0,...,\lambda_n} * \gamma_{n+1}$ where $\gamma_{\lambda_0,...,\lambda_n} = \gamma \circ P_n^{-1}$ is a Gaussian measure with covariance operator*

$$R_{\lambda_0,...,\lambda_n} : f \in X^* \quad \to \quad \sum_{k=0}^n \lambda_k \langle x_k, f \rangle_{X,X^*} x_k.$$

Furthermore, we have $\gamma_{n+1} = \gamma \circ (I - P_n)^{-1}$ and the relation

$$R_\gamma = R_{\lambda_0,...,\lambda_n} + R_{\gamma_{n+1}}.$$

(6) *The Cameron-Martin space $H(\gamma)$ is decomposed as*

$$H(\gamma) = span(h_0, ..., h_n) \oplus H(\gamma_{n+1}),$$

where $H(\gamma_{n+1}) = (I - Q_n)(H(\gamma))$ equipped with the inner product of $H(\gamma)$ is the Cameron-Martin space of the Gaussian measure γ_{n+1}.

(7) *Let $x_n^* = (I - P_{n-1})^* f_n$ for $n \geq 0$. Then, $\forall n, R_\gamma x_n^* = \lambda_n x_n$. The random variables x_n^* are independent $\mathcal{N}(0, \lambda_n)$, and*

$$\forall n, \; P_n x = \sum_{k=0}^n \langle x, x_k^* \rangle_{X,X^*} x_k.$$

For the computation of the dual basis $(x_n^*)_n$, we have the recurrence formula

$$x_n^* = f_n - P_{n-1}^* f_n$$

with $P_{n-1}^* f_n = \sum_{k=0}^{n-1} \langle x_k, f_n \rangle_{X,X^*} x_k^*$ and $x_0^* = f_0$.

Furthermore, $\gamma_{\lambda_0,...,\lambda_n} = \gamma_{\lambda_0} * ... * \gamma_{\lambda_n}$ where γ_{λ_n} is the distribution of the random vector $x \to \langle x, x_n^* \rangle_{X,X^*} x_n$ for all n.

(8) *Let $h_n^* = \sqrt{\lambda_n}^{-1} x_n^*$ for $n \geq 0$. Then, we have $R_\gamma h_n^* = h_n$, and the random variables h_n^* are independent $\mathcal{N}(0,1)$.*

(9) *For each $t = (t_0, ..., t_n) \in \mathbb{R}^{n+1}$, denote by $\sum_{k=0}^n t_k x_k + \gamma_{n+1}$ the Gaussian measure on X centered at $\sum_{k=0}^n t_k x_k$ with covariance operator $R_{\gamma_{n+1}}$. Then, $\gamma^t = \sum_{k=0}^n t_k x_k + \gamma_{n+1}$ is the conditional probability distribution of $x \in X$ given $x_0^*(x) = t_0, ..., x_n^*(x) = t_n$:*

$$\forall B \in \mathcal{B}(X), \; \gamma^t(B) = \gamma_{n+1}\left(B - \sum_{k=0}^n t_k x_k \right) = \gamma(B | x_0^* = t_0, ..., x_n^* = t_n).$$

The deconditioning formula is

$$\gamma(B) = \int_{\mathbb{R}^n} \gamma^t(B) \prod_{k=0}^n \frac{e^{-\frac{t_k^2}{2\lambda_k}}}{\sqrt{2\pi\lambda_k}} dt_k$$

This theorem is a straightforward extension of lemma 3.2 and a proof is given in the appendix. It remains to see that this decomposition is complete, namely that we have

$$\gamma = *_n \gamma_{\lambda_n}$$

according to the decomposition of the covariance operator

$$R_\gamma = \sum_n \lambda_n \langle x_n, . \rangle_{X,X^*} x_n.$$

3.3. **Asymptotic analysis.** In this section, we suppose that $H(\gamma)$ is infinite-dimensional and we use notations of the previous section. The two following lemmas will be essential for the main result of this paper (theorem 3.6).

Lemma 3.4. *We have $B_{H(\gamma_n)} = B_{H(\gamma)} \cap span(h_0, ..., h_{n-1})^\perp$ for all n and*

$$(3.1) \qquad \sqrt{\lambda_n} = \sup_{f \in B_{X^*}} \sup_{h \in B_{H(\gamma_n)}} \langle h, f \rangle_{X,X^*}.$$

Proof of lemma 3.4. Since $H(\gamma) = span(h_0, ..., h_{n-1}) \oplus H(\gamma_n)$ and $\|.\|_{\gamma_n} = \|.\|_\gamma$ on $H(\gamma_n)$ (see theorem 3.3, assertion (6)), we get

$$B_{H(\gamma)} \cap span(h_0, ..., h_{n-1})^\perp = B_{H(\gamma_n)}.$$

But, for $h \in H(\gamma_n)$, $\langle h, f \rangle_{X,X^*} = \langle h, R_{\gamma_n} f \rangle_{\gamma_n}$ and $\sup_{h \in B_{H(\gamma_n)}} \langle h, f \rangle_{X,X^*}$ is attained for $h = \frac{R_{\gamma_n} f}{\|R_{\gamma_n} f\|_{\gamma_n}}$ (if $R_{\gamma_n} f \neq 0$). Thus, $\sup_{h \in B_{H(\gamma_n)}} \langle h, f \rangle_{X,X^*} = \sqrt{\langle R_{\gamma_n} f, f \rangle_{X,X^*}}$. $\square$

Lemma 3.5. *The sequence $(\lambda_n)_{n \geq 0}$ is non-increasing and $\lambda_n \to 0$.*

Proof of lemma 3.5. By lemma 3.4 and the expression 3.1, we see that $\lambda_{n+1} \leq \lambda_n$. Moreover, (h_n) is an orthonormal system in $H(\gamma)$, hence

$$\forall f \in X^*, \ \langle h_n, f \rangle_{X,X^*} = \langle h_n, R_\gamma f \rangle_\gamma \to 0,$$

as a consequence of Bessel's inequality. In other words, we have that $h_n \rightharpoonup 0$ for the weak topology of X. Since the unit ball of $H(\gamma)$ is precompact in X (corollary 3.2.4 p.101 in [2]), we can extract a subsequence $(h_{n_k})_k$ such that $h_{n_k} \to_k h_\infty$ for the strong topology of X. By unicity of limit in the topological vector space X equipped with the weak topology, we deduce that $h_\infty = 0$ in X. Therefore, $\|h_{n_k}\|_X = \sqrt{\lambda_{n_k}} \to_k 0$, which ends the proof. $\square$

The two above lemmas are the ingredients to prove now that the orthonormal family $(h_n)_n$ is a Hilbert basis of $H(\gamma)$ in $R_\gamma(X^*)$ as it is discussed in [14].

Theorem 3.6. *$(h_n)_{n \geq 0} = (R_\gamma h_n^*)_{n \geq 0}$ is a Hilbert basis of $H(\gamma)$.*

Proof of theorem 3.6. Let $h \in H(\gamma)$ such that $\forall n \in \mathbb{N}, \ \langle h, h_n \rangle_\gamma = 0$. Then, using lemma 3.4, we have

$$\forall n \in \mathbb{N}, \ \forall f \in B_{X^*}, \ \langle h, f \rangle_{X,X^*} \leq \sqrt{\lambda_n} \|h\|_\gamma,$$

which implies that $\langle h, f \rangle_{X,X^*} = 0$ for all $f \in X^*$. Therefore, $h = 0$ and $span(h_n, \ n \geq 0)$ is dense in $H(\gamma)$. $\square$

We give now the two claimed results of this paper.

Corollary 3.7. *The covariance operator can be decomposed as follows*

$$R_\gamma = \sum_{n \geq 0} \lambda_n \langle x_n, . \rangle_{X, X^*} x_n,$$

where the convergence is in $\mathcal{L}(X^*, X)$. More precisely, the nth step truncation error is

$$\left\| R_\gamma - \sum_{k=0}^{n} \lambda_k \langle x_k, . \rangle_{X, X^*} x_k \right\| = \lambda_{n+1},$$

where $\|\cdot\|$ stands for the operator norm in $\mathcal{L}(X^*, X)$.

Proof of corollary 3.7. From theorem 3.6, we know that $(h_n)_n$ is a Hilbert basis of $H(\gamma)$. It suffices to write

$$\forall f \in X^*, \ R_\gamma f = \sum_{n \geq 0} \langle R_\gamma f, h_n \rangle_\gamma h_n,$$

and use the reproducing property. The truncation error norm is

$$\left\| R_\gamma - \sum_{k=0}^{n} \lambda_k \langle x_k, . \rangle_{X, X^*} x_k \right\| = \sup_{f \in B_{X^*}} \| R_{\gamma_{n+1}} f \|_X.$$

But,

$$\| R_{\gamma_{n+1}} f \|_X = \sup_{g \in B_{X^*}} \langle R_{\gamma_{n+1}} f, g \rangle_{X, X^*} \leq \lambda_{n+1}$$

by the Cauchy-Schwarz inequality. Since $R_{\gamma_{n+1}} f_{n+1} = \lambda_{n+1} x_{n+1}$ and $\| x_{n+1} \|_X = 1$, we have $\| R_{\gamma_{n+1}} f_{n+1} \|_X = \lambda_{n+1}$. Hence

$$\left\| R_\gamma - \sum_{k=0}^{n} \lambda_k \langle x_k, . \rangle_{X, X^*} x_k \right\| = \lambda_{n+1} \to 0.$$

$$\square$$

Corollary 3.8. *Remind the definition $h_n^* = \sqrt{\lambda_n}^{-1} x_n^*$ with $x_n^* = (I - P_{n-1})^* f_n$ for $n \geq 1$ and $x_0^* = f_0$. Then, we have the decomposition in X*

$$x = \sum_n \langle x, h_n^* \rangle_{X, X^*} h_n, \ \gamma \ a.e.,$$

where the random variables h_n^* are independent $\mathcal{N}(0, 1)$. In equivalent form, let $(\xi_n)_n$ be a sequence of independent standard normal variables on $(\Omega, \mathcal{F}, \mathbb{P})$. Then the random series

$$\sum_n \sqrt{\lambda_n} \xi_n(\omega) x_n$$

defines a X-valued random Gaussian vector with distribution γ.

4. Decomposition of the classical Wiener measure

Let γ be the standard Wiener measure on $X = \mathcal{C}([0, 1], \mathbb{R})$, the space of all real continuous functions on the interval $[0, 1]$ which is a Banach space if equipped with the supremum norm. The Riesz-Markov representation theorem allows to identify X^* with the linear space of all bounded signed measures on $[0, 1]$ equipped with the norm of total variation. In this context, the dual pairing is

$$\forall x \in X, \ \forall \mu \in X^*, \ \langle x, \mu \rangle_{X, X^*} = \int_0^1 x(t) \mu(dt).$$

The Cameron-Martin space associated to γ is the usual Sobolev space $H_0^1([0,1],\mathbb{R})$, defined by

$$H_0^1([0,1],\mathbb{R}) = \left\{ f \in X, \ \forall t \in [0,1], \ f(t) = \int_0^t f'(s)ds, \ f' \in L^2([0,1],\mathbb{R}) \right\}$$

and associated inner product $\langle f_1, f_2 \rangle_\gamma = \langle f_1', f_2' \rangle_{L^2}$. The covariance operator R_γ satisfies

$$\langle R_\gamma \mu, \mu \rangle_{X,X^*} = Var\left(\int_0^1 W_t \mu(dt) \right)$$

where $(W_t)_{t \in [0,1]}$ is the standard Wiener process. Using Fubini's theorem, we easily get

$$\langle R_\gamma \mu, \mu \rangle_{X,X^*} = \iint_{[0,1]^2} t \wedge s \mu(dt)\mu(ds) = \int_0^1 \mu([u,1])^2 du.$$

Hence, $(R_\gamma \mu)'(t) = \mu([t,1])$ almost everywhere in $[0,1]$, and $R_\gamma \mu : t \in [0,1] \to \int_0^t \mu([u,1])du$. Consider now the initial step of the decomposition, that is find $f_0 = \mu_0 \in B_{X^*}$ such that

$$\langle R_\gamma \mu_0, \mu_0 \rangle_{X,X^*} = \sup_{\mu \in B_{X^*}} \langle R_\gamma \mu, \mu \rangle_{X,X^*}.$$

Since $\forall \mu \in B_{X^*}, \forall u \in [0,1], \ |\mu([u,1])| \leq 1$, the unique measure into B_{X^*} maximizing $\langle R_\gamma \mu, \mu \rangle_{X,X^*} = \int_0^1 \mu([u,1])^2 du$ is $\mu_0 = \delta_1$. Moreover,

$$\lambda_0 = \langle R_\gamma \mu_0, \mu_0 \rangle_{X,X^*} = Var(W_1) = 1$$

is the variance of the Wiener process at point $t = 1$. Since $\mu \to \langle R_\gamma \mu, \mu \rangle_{X,X^*}$ is a non-negative quadratic functional, an usual argument shows directly that μ_0 must be an extremal point of B_{X^*}. Thus $\mu_0 = \delta_{t_0}$ for some point $t_0 \in [0,1]$. And clearly, $t_0 = 1$, corresponding to the maximum of variance of the Wiener process. So, we have $\lambda_0 = 1$, $f_0 = \mu_0 = \delta_1$. Using the fact that

$$R_\gamma \delta_t : s \in [0,1] \to \langle R_\gamma \delta_t, \delta_s \rangle_{X,X^*} = Cov(W_t, W_s) = t \wedge s,$$

we get $x_0 = (t \in [0,1] \to t)$ and $h_0 = x_0$ (since $\lambda_0 = 1$). Now, we have $P_0 x : t \in [0,1] \to \langle x, f_0 \rangle_{X,X^*} x_0(t) = x(1)t$ and $(I - P_0)x$ is the function $t \in [0,1] \to x(t) - x(1)t$. From this, we see that $\gamma_1 = \gamma \circ (I - P_0)^{-1}$ is the Gaussian measure associated to the Brownian bridge $(B_t)_{t \in [0,1]}$ with covariance kernel

$$K_1 : (t,s) \in [0,1]^2 \to Cov(B_t, B_s) = t \wedge s - ts.$$

Using now the fact that $\mu \to \langle R_{\gamma_1} \mu, \mu \rangle_{X,X^*}$ is a non-negative quadratic functional, we see that $f_1 = \mu_1 = \delta_{t_1}$ where $t_1 = \frac{1}{2}$ is the maximum of variance of the Brownian bridge B. Hence, we get $\lambda_1 = \frac{1}{4}$, $x_1 = (t \to 4(t \wedge \frac{1}{2} - \frac{t}{2}))$ (by the relation $\lambda_1 x_1 = R_{\gamma_1} \delta_{\frac{1}{2}}$) and $h_1 = \frac{1}{2} x_1$. Furthermore, $x_1^* = \delta_{t_1} - \frac{1}{2} \delta_{t_0}$ and $\gamma_2 = \gamma \circ (I - P_1)^{-1}$ is the Gaussian distribution of the process $(I - P_1)W : t \to W_t - W_1 x_0(t) - (W_{\frac{1}{2}} - \frac{1}{2} W_1)x_1(t)$. By the assertion 9 of theorem 3.3, γ_2 is the conditional distribution of W given $W_1 = 0, W_{\frac{1}{2}} = 0$. Using this interpretation, scale-invariance and spatial Markov properties of the Wiener process, we immediately get

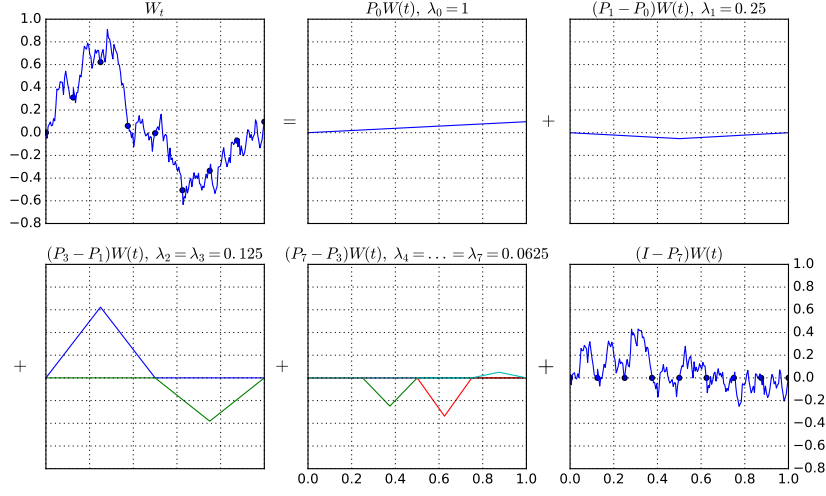$$\lambda_n = \frac{1}{2^{p+2}} \quad \text{for } n = 2^p + k, \ k = 0, ..., 2^p - 1 \ \text{ and } p \geq 0.$$

FIGURE 1. Decomposition of the standard Wiener measure on the 8 first steps.

Furthermore, the Hilbert basis $(h_n)_{n\geq 0}$ of $H(\gamma)$ is given by $h_0(t) = t$ and $h_n(t) = \int_0^t h'_n(s)ds$, $n \geq 1$, where

$$h'_n(s) = \begin{cases} \sqrt{2^p} \text{ for } \frac{2k}{2^{p+1}} \leq s \leq \frac{2k+1}{2^{p+1}} \\ -\sqrt{2^p} \text{ for } \frac{2k+1}{2^{p+1}} < s \leq \frac{2k+2}{2^{p+1}} \\ 0 \text{ otherwise} \end{cases},$$

if $n = 2^p + k$, $k = 0, ..., 2^p - 1$ and $p \geq 0$. The family $(h'_n)_{n\in\mathbb{N}}$ is the usual Haar basis of $L^2([0,1], \mathbb{R})$. The functions $(x_n)_{n\geq 0}$ are Schauder's functions

$$x_n(t) = \sqrt{2^{p+2}} h_n(t)$$

corresponding to *hat functions* of height 1 and lying above the intervals $\left[\frac{k}{2^p}, \frac{k+1}{2^p}\right]$ ($n = 2^p + k$). The resulting decomposition $\sum_n \sqrt{\lambda_n} \xi_n(\omega) x_n$ is the famous Lévy-Ciesielski construction of Brownian motion on the interval $[0,1]$ (see [10]). The 8 first steps (and the associated residual) of this decomposition are illustrated in figure 1.

5. COMMENTS

(1) For γ a Gaussian measure on a separable Hilbert space X, corollary 3.7 is equivalent to the spectral theorem applied to the self-adjoint compact operator R_γ. In the Banach case, corollary 3.7 says that

$$R_\gamma = \sum_{n\geq 0} \lambda_n \langle x_n, . \rangle_{X,X^*} x_n,$$

where $(\lambda_n)_n$ is a non-increasing sequence that converges to zero and $(x_n)_n$ is a sequence of unit norm vectors in X and orthogonal in $H(\gamma)$. Furthermore, we have the same formula for the error (see comments below of its

importance for applications):

$$\left\| R_\gamma - \sum_{k=0}^{n} \lambda_k \langle x_k, . \rangle_{X,X^*} x_k \right\| = \lambda_{n+1}.$$

Interpretation of the pairs (λ_n, x_n) for each n is the following: for $n = 0$, x_0 is a (unit) direction vector for a line in X that has the largest variance possible $(= \lambda_0)$ by a projection of norm one (namely, the projection P_0 in theorem 3.3). Remark that P_0 of norm one means P_0 orthogonal or self-adjoint in the Hilbert case. By considering the measure $\gamma_1 = \gamma \circ (I - P_0)^{-1}$, the vector x_1 is the direction vector for a line in the subspace $(I - P_0)X$ that has the largest variance possible and so on. In the Hilbert case, this decomposition process is known as (functional) principal component analysis.

(2) In this work, we assume the Radon measure γ to be Gaussian. By a slight modification of the proof of lemma 3.1, the decomposition is valid if we assume only $\int_X \|x\|^2 \gamma(dx) < +\infty$ and results have to be interpreted in a mean-square sense (in particular, independence becomes non correlation and last parts of lemma 3.1 and theorem 3.3 on conditioning are valid only in the Gaussian case).

(3) The random series representation $\sum_{n \geq 0} \sqrt{\lambda_n} \xi_n(\omega) x_n$ in corollary 3.8 is a generalization of the Karhunen-Loève expansion based on the corresponding decomposition of the covariance operator $R_\gamma = \sum_{n \geq 0} \lambda_n \langle x_n, . \rangle_{X,X^*} x_n$.

(4) The decomposition of the classical Wiener measure shows that

$$\sum_n \lambda_n = 1 + \frac{1}{4} + 2 \times \frac{1}{8} + 4 \times \frac{1}{16} + ... = +\infty$$

due to the "multiplicity" of the values λ_n. In the Hilbert case, this sum is always finite and is the trace of the operator R_γ. Furthermore, this finite-trace property is characteristic of Gaussian measures on Hilbert spaces. Such a characterization in the Banach case is still an open problem.

(5) Gaussian hypothesis is motivated by applications both in Gaussian process regression (or Kriging, see [11]) and Bayesian inverse problems ([13]). As theorem 3.3 indicates, we are interested in an efficient algorithm to construct a design of experiments (see [4]) or a training set (functionals $(f_n)_n$ or, equivalently, $(x_n^*)_n$). Error expression $\|R_\gamma - \sum_{k=0}^{n} \lambda_k \langle x_k, . \rangle_{X,X^*} x_k\| = \sup_{f \in B_{X^*}} \|R_{\gamma_{n+1}} f\|_X = \lambda_{n+1}$ in corollary 3.7 says that we have a precise quantification of uncertainty in terms of confidence interval in the Gaussian case.

6. Conclusion

In this work, we suggest a Karhunen-Loève expansion for a Gaussian measure on a separable Banach space based on a corresponding decomposition of its covariance operator. In some sense, this decomposition generalizes the Hilbert case. Lévy's construction of Brownian motion appears to be a particular case of such an expansion. Finally, we believe that this result will be useful both in pure and applied mathematics since it provides a canonical representation of Gaussian measures on separable Banach spaces.

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Proofs

Proof of lemma 3.2. (1) Since $R_\gamma f_0 = \lambda_0 x_0$, we have

$$\lambda_0 \langle x_0, f_0 \rangle_{X,X^*} = \langle R_\gamma f_0, f_0 \rangle_{X,X^*} = \lambda_0$$

and $\lambda_0 > 0$ implies $\langle x_0, f_0 \rangle_{X,X^*} = 1$. The second equality is obtained from the definition of h_0 and the reproducing property:

$$\|h_0\|_\gamma^2 = \langle h_0, h_0 \rangle_\gamma = \langle x_0, \lambda_0 x_0 \rangle_\gamma = \langle x_0, R_\gamma f_0 \rangle_\gamma = \langle x_0, f_0 \rangle_{X,X^*} = 1.$$

(2) Since $P_0 x_0 = \langle x_0, f_0 \rangle_{X,X^*} x_0 = x_0$, we have $P_0^2 = P_0$ and P_0 is clearly the projection onto $\mathbb{R}x_0$ along the null space of $f_0 \in X^*$. Now, if $h \in H(\gamma)$, we get by the reproducing property:

$$P_0 h = \langle h, R_\gamma f_0 \rangle_\gamma x_0 = \langle h, \lambda_0 x_0 \rangle_\gamma x_0 = \langle h, h_0 \rangle_\gamma h_0 = Q_0 h.$$

(3) As bounded linear transformations of a (centered) Gaussian measure, both γ_{λ_0} and γ_1 are (centered) Gaussian measures. Consider the decomposition in X^*:

$$f = P_0^* f + (I - P_0^*)f.$$

Now, the random variable $P_0^* f = \langle x_0, f \rangle_{X,X^*} f_0$ is Gaussian with variance $\langle R_{\gamma_{\lambda_0}} f, f \rangle_{X,X^*} = \lambda_0 \langle x_0, f \rangle_{X,X^*}^2$ and $(I - P_0^*)f = f - \langle x_0, f \rangle_{X,X^*} f_0$ is Gaussian with variance $\langle R_{\gamma_1} f, f \rangle_{X,X^*}$. To show that $P_0^* f$ and $(I - P_0^*)f$

are independent, we compute their covariance:

$$\int_X \langle x, P_0^* f \rangle_{X,X^*} \langle x, (I - P_0^*) f \rangle_{X,X^*} \gamma(dx)$$

$$= \int_X \langle x_0, f \rangle_{X,X^*} \langle x, f_0 \rangle_{X,X^*} \left(\langle x, f \rangle - \langle x_0, f \rangle \langle x, f \rangle \right) \gamma(dx)$$

$$= \langle x_0, f \rangle_{X,X^*} \langle R_\gamma f_0, f \rangle_{X,X^*} - \lambda_0 \langle x_0, f \rangle_{X,X^*}^2$$

$$= 0.$$

Using the characteristic function of γ, we get by independence

$$\hat{\gamma}(f) = \int_X e^{i \langle x, (P_0^* f + (I - P_0^*) f) \rangle_{X,X^*}} \gamma(dx) = \hat{\gamma_{\lambda_0}}(f) \hat{\gamma_1}(f).$$

This proves $\gamma = \gamma_{\lambda_0} * \gamma_1$ and also $R_\gamma = R_{\gamma_{\lambda_0}} + R_{\gamma_1}$.

(4) Consider the orthogonal decomposition $H(\gamma) = \mathbb{R} h_0 \oplus H_1$ where $H_1 = (\mathbb{R} h_0)^\perp$. Since $R_{\gamma_{\lambda_0}} f = \lambda_0 \langle x_0, f \rangle_{X,X^*} x_0 = \langle R_\gamma f, h_0 \rangle_\gamma h_0$ is the orthogonal projection of $R_\gamma f$ onto $\mathbb{R} h_0$, we see that $R_\gamma f = R_{\lambda_0} f + R_{\gamma_1} f$ is the corresponding orthogonal decomposition of $R_\gamma f$. Therefore, by the Pythagorean theorem,

$$\|R_\gamma f\|_\gamma^2 = \|R_{\gamma_0} f\|_\gamma^2 + \|R_{\gamma_1} f\|_\gamma^2.$$

Now, using the relation $R_{\gamma_{\lambda_0}} f = \lambda_0 \langle x_0, f \rangle_{X,X^*} x_0$, we get $\|R_{\gamma_{\lambda_0}} f\|_\gamma^2 = \lambda_0 \langle x_0, f \rangle_{X,X^*}^2 = \langle R_{\gamma_{\lambda_0}} f, f \rangle_{X,X^*} \ (= \|R_{\gamma_{\lambda_0}} f\|_{\gamma_{\lambda_0}}^2)$, thus

$$\|R_{\gamma_1} f\|_\gamma^2 = \langle R_\gamma f, f \rangle_{X,X^*} - \langle R_{\lambda_0} f, f \rangle_{X,X^*} = \langle R_{\gamma_1} f, f \rangle_{X,X^*}.$$

Using the reproducing property in the Cameron-Martin space $H(\gamma_1)$, we get $\|R_{\gamma_1} f\|_\gamma^2 = \|R_{\gamma_1} f\|_{\gamma_1}^2$. Since $R_{\gamma_1}(X^*)$ is dense in $H(\gamma_1)$, we conclude that $H(\gamma_1)$ is a subspace of H_1 and, in particular, $\langle ., . \rangle_{\gamma_1} = \langle ., . \rangle_\gamma$. Finally, $H(\gamma_1) = H_1$ by density of $R_\gamma(X^*)$ in $H(\gamma)$.

(5) Using $\gamma = \gamma_{\lambda_0} * \gamma_1$, we can write for all $B \in \mathcal{B}(X)$:

$$\gamma(B) = \int_X \gamma_1(B - tx_0) \frac{e^{-\frac{t^2}{\lambda_0}}}{\sqrt{2\pi\lambda_0}} dt.$$

Since $f_0 \sim N(0, \lambda_0)$, we deduce that $\gamma(B|f_0 = t) = \gamma_1(B - tx_0)$ (as a regular conditional probability).

$\square$

Proof of theorem 3.3. (1) For $n \in \mathbb{N}$, $\|h_n\|_\gamma = 1$ by construction. If $n < m$, remark that $h_n \in span(h_0, ..., h_{m-1}) = H(\gamma_m)^\perp$ to get $\langle h_n, h_m \rangle_\gamma = 0$.

(2) By definition of x_n, we have $\langle x_n, f_n \rangle_{X,X^*} = 1$. Now, the reproducing property gives

$$\forall f \in B_{X^*}, \ \langle x_n, f \rangle_{X,X^*} = \langle x_n, R_{\gamma_n} f \rangle_{\gamma_n} \leq \|x_n\|_{\gamma_n} \sqrt{\langle R_{\gamma_n} f, f \rangle_{X,X^*}}.$$

Using the relations $\langle R_{\gamma_n} f, f \rangle_{X,X^*} \leq \lambda_n$ and $\|\sqrt{\lambda_n} x_n\|_{\gamma_n} = \|h_n\|_\gamma = 1$, we get $\langle x_n, f \rangle_{X,X^*} \leq 1$. This proves that $\|x_n\|_{X^*} = \langle x_n, f_n \rangle_{X,X^*} = 1$.

For $k > l$, $h_k \in H(\gamma_l)$ and the reproducing property gives

$$\sqrt{\lambda_k} \langle x_k, f_l \rangle_{X,X^*} = \langle h_k, R_{\gamma_l} f_l \rangle_{\gamma_l} = \sqrt{\lambda_l} \langle h_k, h_l \rangle_\gamma = 0.$$

Hence $\langle x_k, f_l \rangle_{X,X^*} = 0$ since $\lambda_k > 0$.

(3) For $h \in H(\gamma)$, we have
$$Q_n h = \sum_{k=0}^{n} \langle h, \lambda_k x_k \rangle_\gamma x_k = \sum_{k=0}^{n} \langle h, R_{\gamma_k} f_k \rangle_\gamma x_k.$$
According to the orthogonal decomposition
$$H(\gamma) = span(h_0, ..., h_{k-1}) \oplus H(\gamma_k),$$
we get that
$$\langle h, R_{\gamma_k} f_k \rangle_\gamma = \langle h - Q_{k-1}h, R_{\gamma_k} f_k \rangle_{\gamma_k} = \langle h - Q_{k-1}h, f_k \rangle_{X,X^*},$$
which proves the result.

(4) Let $x \in X$ then $P_n x \in span(x_0, ..., x_n) = range(Q_n)$ thus $P_n x \in H(\gamma)$ and $P_n(P_n x) = Q_n(P_n x) = P_n x$. Clearly, we have:
$$\bigcap_{k=0}^{n} \ker(f_k) \subset \ker(P_n).$$
Conversely, if $P_n x = 0$ then $P_k x = 0$ for all $k \in [0,n]$ and $0 = \langle x - P_{k-1}x, f_k \rangle_{X,X^*} = \langle x, f_k \rangle_{X,X^*}$, hence $\ker(P_n) \subset \bigcap_{k=0}^{n} \ker(f_k)$.

(5) Since $Q_n = P_n$ on $H(\gamma)$, remark first that $R_{\gamma_{\lambda_0,...,\lambda_n}} = R_\gamma P_n^* = Q_n R_\gamma$ and also $R_{\gamma_{n+1}} = R_\gamma(I - P_n)^* = (I - Q_n)R_\gamma$. In particular, $R_{\gamma_{\lambda_0,...,\lambda_n}} f = \sum_{k=0}^{n} \langle R_\gamma f, h_k \rangle_\gamma h_k = \sum_{k=0}^{n} \lambda_k \langle x_k, f \rangle_{X,X^*} x_k$. Consider now the decomposition for $f \in X^*$:
$$f = P_n^* f + (I - P_n)^* f.$$
The random variable $P_n^* f$ is Gaussian with variance $\langle R_{\gamma_{\lambda_0,...,\lambda_n}} f, f \rangle_{X,X^*}$ and $(I - P_n)^* f$ is Gaussian with variance $\langle R_{\gamma_{n+1}} f, f \rangle_{X,X^*}$. Since $\langle R_\gamma P_n^* f, (I - P_n)^* f \rangle_{X,X^*} = \langle (I - Q_n)Q_n R_\gamma f, f \rangle_{X,X^*} = 0$, the random variables $P_n^* f$ and $(I - P_n)^* f$ are independent and we conclude as in lemma (3.2).

(6) The proof is similar to the proof of (4) in lemma (3.2). Introduce the space $H_{n+1} = span(h_0, ..., h_n)^\perp$, we have that $(R_{\gamma_{n+1}}(X^*), \langle ., .\rangle_{\gamma_{n+1}})$ is a subspace of H_{n+1}, which is sufficient to prove $H(\gamma_{n+1}) = H_{n+1}$ as Hilbert spaces.

(7) For $n \geq 0$ and $h \in H(\gamma)$, we write $\langle h, R_\gamma x_n^* \rangle_\gamma = \langle h, (I - P_{n-1})^* f_n \rangle_{X,X^*}$, thus $\langle h, R_\gamma x_n^* \rangle_\gamma = \langle (I - Q_{n-1})h, f_n \rangle_{X,X^*} = \langle (I - Q_{n-1})h, R_{\gamma_n} f_n \rangle_\gamma$. Using now the relation $R_{\gamma_n} f_n = \lambda_n x_n$, we finally get $\langle h, R_\gamma x_n^* \rangle_\gamma = \langle h, \lambda_n x_n \rangle_\gamma$, which proves $R_\gamma x_n^* = \lambda_n x_n$. In particular, $\langle R_\gamma x_n^*, x_n^* \rangle_{X,X^*} = \lambda_n$. In the same way, we get $\langle R_\gamma x_m^*, x_n^* \rangle_{X,X^*} = 0$ if $m \neq n$. Hence, the random variables x_n^* are independent with respective variance λ_n. The computation of this sequence comes from the identity $P_n^* f = \sum_{k=0}^{n} \langle x_k, f \rangle_{X,X^*} x_k^*$.

(8) This is a reformulation of the previous statement about the sequence $(x_n^*)_n$.

(9) This last assertion is a direct consequence of (5) and (7).

$\square$

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