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Reappraisal of upscaling descriptors for transient two-phase flows in fibrous media

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Abstract

Transient two-phase flows within fibrous media are considered at local scale. Upscaling these flows constitute a key procedure towards a tractable description in an industrial context. However, the task remains challenging as a time-dependent behaviour is observed within a geometrically complex structure with interplay of various physical phenomena (capillary effects, viscous dissipation,...). **The usual upscaling strategies, encountered in both soil sciences and composite materials communities are reviewed, compared, and finally adapted to reach a method that is relevant to describe fibrous media imbibition. Using finite element flow simulations on statistical representative volume elements, the proposed approach first considers several definitions for saturation in order to characterise the flow dynamics as well as the characteristic length associated with the transient behaviour.** Next, two methods are proposed to assess a resulting capillary pressure, demonstrating the importance to properly define the capillary pressure acting on the interface. The first one considers the mean pressure jump at the interface while the second one uses a machine-learning technique, namely Gaussian Process Regression, to retrieve the mean curvature of the interface. Those methods are found to be both consistent and in agreement with the results from the literature.

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047 Finally, a novel approach that stochastically describes the position of the
 048 flow front through a presence distribution is detailed. The spread of the
 049 front can be compared to the saturation length and its value has been
 050 found to be small enough to be neglected at upper scale, justifying the
 051 use of sharp interface models for similar porous media and flow settings.

052 **Keywords:** Upscaling, Capillary pressure, Two-phase flow simulations,
 053 Gaussian Process Regression

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058 Notations and abbreviations (text order)

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RVE Representative Volume Element

S_L Liquid saturation of the volume

S_L^{max} Maximum liquid saturation of the volume

t Time variable

Ca Capillary number

η_i Viscosity of phase i

v_{in} Inlet velocity

γ_j Surface tension coefficient of interface j

P_{vol}^c Resulting capillary pressure (volume definition)

p Fluid pressure field

$\langle \cdot \rangle^i$ Volume averaging operator over phase i

Ω_i Domain associated with phase i

$|\omega|$ Volume/surface of domain ω

$P_{vol,dyn}$ Dynamic capillary pressure (volume definition)

τ Relaxation coefficient associated with $P_{vol,dyn}^c$

$[[p]]_j$ Pressure jump at interface Γ_j

\mathcal{C} Mean curvature

$\langle \cdot \rangle^{LV}$ Surface averaging operator over the liquid-vapor interface Γ_{LV}

P_p^c	Resulting capillary pressure (pressure jump definition)	093
P_C^c	Resulting capillary pressure (mean curvature definition)	094
Ω	Computational domain	095
ρ_i	Density of phase i	096
\bar{r}	Average fibre radius	097
\mathbf{v}	Fluid velocity field	098
ϕ	Level-set field	099
ASGS	Algebraic SubGrid Scale	100
SUPG	Streamline Upwind Petrov-Galerkin	101
V_f	Fibre volume ratio	102
SRVE	Statistical Representative Volume Element	103
L	Characteristic length of the computational domain	104
$s_L(A)$	Liquid saturation of section A	105
$s_L^{max}(A)$	Maximum liquid saturation of section A	106
R	Ratio between $s_L(A)$ and $s_L^{max}(A)$	107
ℓ_s	Saturation length	108
GPR	Gaussian Process Regression	109
\mathcal{F}	Area containing the flow front	110
$\mathbf{x}_i^{\mathcal{F}}$	Coordinates of the vertices that shape the flow front	111
$I_{\mathbf{x},\mathcal{F}}$	Random variable which realisations give $\mathbf{x}_i^{\mathcal{F}}$	112
ℓ_s^*	Saturation length averaged over time	113
P_p^{c*}	Asymptotic value of P_p^c	114
P_C^{c*}	Asymptotic value of P_C^c	115
μ	Mean value of the flow front distribution	116
σ	Standard deviation of the flow front	117
σ^*	Asymptotic value of σ	118
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1 Introduction

Multiphase flows in fibrous media are commonly observed in numerous fields going from soil science [1–3] to composite manufacturing processes [4, 5] where a carbon fibre preform that initially contains rarefied air is filled with a liquid resin. A multiphase flow resin/air within a porous fibrous medium is thus observed. This medium naturally shows several scales of description, starting from the scale of the carbon fibre ($\sim \mu\text{m}$) to the scale of the industrial part ($\sim \text{m}$). As flow models must be adapted to the scale of representation, connecting those microscopic and macroscopic scales has been a major concern in the scientific community. As a first approach, a permeability tensor that represents the ability of the fibrous structure to be crossed by a fluid is generally studied. This concept has been first introduced following Darcy’s works to macroscopically describe a monophasic steady flow in a porous medium [6]. Besides, the complexity of a multiphase flow can hardly be reduced to a single tensor. Such flows are indeed considerably more challenging to describe as several phases are observed with a moving interface. The observed behaviour becomes non-linear, time-dependent and sensitive to many parameters such as fluid properties or boundary conditions. In addition to this, the vicinity between carbon fibres, around few micrometers, leads to consider capillary effects and consequently a sensitivity to surface tension coefficients [7, 8].

From early theoretical works, upscaling strategies from Representative Volume Elements (RVE) have been proposed to transpose the microscopic description of multiphase flows in porous media towards an upper scale [3, 9–11]. Those have been mainly developed by the hydrogeology community for the study of flows within soils or rocks. Later on, the composite materials community have developed its own approaches, that are particularly suited for the study of fibrous materials impregnation but that may suffer from a lack of

sound theoretical ground. The novelty of this contribution consists in operating an explicit connection between both types of approaches, so as to retrieve a rigorous, precise, and complete description that is adapted to the imbibition of fibrous media while carrying the specificities and constraints inherent to composite materials.

1.1 Saturation

The most straightforward upscaling quantity is the liquid saturation $S_L \in [0, 1]$ that describes the proportion of liquid within the poral space. As imbibition is considered here, S_L increases over time from 0 to a maximal value $S_L^{max} = S_L(t \rightarrow \infty)$ obtained when the two-phase flow reaches steadiness. The relation $S_L = S_L(t)$ characterises the global dynamics of the flow. The asymptotic saturation value S_L^{max} is lower than 1 as the flow tends to entrap air bubbles behind the front. This proportion of residual phase at final state is a concern in many fields since it can be associated with a recovery ratio in hydrology [12] or a void content in the composite materials community [13]. As bubble entrapment phenomenon results from velocity inhomogeneity over the volume, S_L^{max} value is expected to be directly dependent on the competition between viscous and capillary effects. This is expressed through the capillary number Ca that is defined here as:

$$Ca = \frac{\eta_L v_{in}}{\gamma_{LV}} \quad (1)$$

where η_L is the liquid viscosity, v_{in} the inlet velocity and γ_{LV} the surface tension coefficient from the liquid-vapor interface.

Studying the saturation finally describes a complex phenomenon through a single time-dependent scalar. It is especially convenient at upper scales where the two-phase flow can be modeled as a transport of saturation in an equivalent homogeneous medium [14]. However, in the context of an upscaling procedure,

231 a global saturation only provides a rough description of the flow without spa-
232 tial information. As a consequence, a first improvement consists in defining
233 saturation at a more local scale. This is observed in the literature related to
234 composite materials processes where local saturation curves are often consid-
235 ered [15–19], they consist in representing saturation as a function of position
236 at a given time. A transition between two saturation regimes is observed, its
237 characteristic width is referred to as *saturation length*. This approach is par-
238 ticularly suited for the type of flow and geometry under consideration, that is
239 to say the impregnation of fibrous reinforcements as encountered in aeronau-
240 tical structural applications and that locally show a statistically homogeneous
241 nature. It thus may be complex to transpose to other specific contexts, like
242 wicking in 3D structures, where further difficulties arise, such as pore delays
243 [20].

257 1.2 Capillary effects

259 Capillary effects rising from surface tension phenomena act as a complemen-
260 tary force in the filling of fibrous microstructures. However, in a more general
261 context, it depends on the fluids under consideration as well as the pore struc-
262 ture. In the context of manufacturing processes of composite materials, it is
263 generally considered as a driving force that helps the impregnation [7]. In
264 any case, this contribution has to be upscaled. This is achieved through the
265 introduction of a *resulting* capillary pressure P^c . Though the *capillary pres-*
266 *sure* term is widely encountered in literature, it may admit several definitions
267 and approaches. In literature and especially in the hydrogeology community,
268 it is generally defined at the volume scale [21]. A first definition P_{vol}^c is thus
269 obtained as the difference between volume-averaged phase pressure:

$$P_{vol}^c = \langle p_V \rangle^V - \langle p_L \rangle^L \quad (2)$$

where p_i is the pressure field associated to phase i . From now on, L will refer to the liquid phase, V to the vapor phase and S to the solid one. Such a definition (Eq.2) requires volume-averaging operator:

$$\langle \cdot \rangle^i = \frac{1}{|\Omega_i|} \int_{\Omega_i} \cdot dV \quad (3)$$

Those volume-defined capillary pressures are generally expressed as a function of the saturation S_L [22]. The determination of capillary pressure-saturation curves constitutes a huge area of research as they are considered to characterise the two-phase flow at a macroscopic level. They finally provide a simple macroscopic relation that is convenient to use in practice especially when transport of saturation is considered.

However, obtaining capillary pressure-saturation curves is challenging for several reasons. First, an hysteresis phenomenon is classically observed between the imbibition and drainage curves [23]. Besides, it has been shown that equilibrium must be reached so that Eq.2 match the capillary pressure [24, 25]. This especially makes the experimental determination of $P_{vol}^c - S_L$ curves very time-consuming since for a given saturation value, the flow may take several hours to stabilise towards a steady state [26]. In parallel, flows observed in practice generally show a transient behaviour where the static equilibrium is never met. This finally leads to consider *dynamic capillary effects* for which a considerable amount of contribution can be found [23, 27, 28]. In the context of these works, the instantaneous difference of phase pressure $P_{vol,dyn}^c$ is then measured and related to the static pressure through the (de)saturation rate

323 [21]:

$$324 \quad P_{vol,dyn}^c = P_{vol}^c - \tau \frac{\partial S_L}{\partial t} \quad (4)$$

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326 where the dynamic coefficient τ controls the rate to reach the equilibrium.
327 The value for this coefficient can span several orders of magnitude and its
328 dependancies are complex and still on study [23, 27–30]. It should be noticed
329 that $P_{vol,dyn}^c$ is sometimes referred to as *dynamic capillary pressure* which is
330 somehow ambiguous as the quantity does not rely on any rigorous justification
331 based on capillary laws.
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339 1.3 Interfacial capillary pressure

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341 In spite of its apparent simplicity and the convenience of its use, a capillary
342 pressure-saturation relationship can finally be complex to determine and raise
343 numerous modelling questions. More generally, assuming that capillary effects
344 match a global difference between phase pressures is not straightforward [31].
345 Mathematically, capillary action is taken into account through the Laplace's
346 law (Eq.5) that only holds at the interface between two phases:
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$$352 \quad \llbracket p \rrbracket_j = \gamma_j \mathcal{C} \quad \text{in} \quad \Gamma_j(t) \quad (5)$$

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355 where $\llbracket p \rrbracket_j$ is the pressure field discontinuity at interface Γ_j , characterised by
356 its surface tension γ_j and by a mean curvature \mathcal{C} .

357
358 As a consequence, a rigorous upscaling procedure cannot retrieve a volume
359 definition of capillary pressure. All these arguments lead to reevaluate the com-
360 mon volume definition of capillary pressure. To be consistent with the physics
361 of the problem, as well as the upscaling procedure, a resulting capillary pres-
362 sure computed at the interface level should be considered [25, 32]. Starting
363 from Eq.5, a surface averaging over the liquid-vapor interface can be carried
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out through an operator $\langle \cdot \rangle^{LV}$:

$$\langle \cdot \rangle^{LV} = \frac{1}{|\Gamma_{LV}|} \int_{\Gamma_{LV}} \cdot dS \quad (6)$$

This gives two other approaches for considering resulting capillary pressure.

A first one consists in averaging the pressure jump [33, 34] while the second integrates the mean curvature over the interface [11, 24, 34, 35]:

$$P_p^c = \langle \llbracket p \rrbracket_{LV} \rangle^{LV} \quad (7)$$

$$P_C^c = \gamma_{LV} \langle \mathcal{C} \rangle^{LV} \quad (8)$$

As capillary pressure becomes defined at interface level, its dependancies to time or saturation can be reappraised. Indeed, capillary pressure does not correspond anymore to a volume scale driving force that may depend on the proportion of each phase. Instead, the resulting capillary action can be expected to be only a function of the porous geometry and surface tension coefficients. This is in agreement with the composite materials literature [7, 36] in which capillary pressure is considered as an intrinsic property of the porous medium and fluids.

1.4 Description of the flow front

Finally, a novel method to characterise the flow front is proposed in this work. As the flow front is fragmented and discontinuous within the complex poral structure, modeling it in a deterministic way may be criticised [19]. Consequently, a statistical modelling is proposed where the flow front is characterised by a presence distribution. At an upper scale, this allows us to

415 assess the mean position of the flow front as well as its spread across the poral
416 structure, which is particularly relevant in the study of complex porous media.
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420 This paper will first recall the numerical strategy for the simulation of
421 transient two-phase flow (Section 2.1). Next, the proposed upscaling procedure
422 will be detailed (Section 2.2). Then the results will be presented (Section 3)
423 and discussed (Section 4).
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2 Materials and methods

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431 The physical modelling of transient two-phase flow is now detailed. Such a
432 problem is solved within a stabilised finite element framework that has been
433 presented in previous studies and that will be briefly recalled here. Particu-
434 lar attention is paid to the generation method of fibrous geometries and to
435 boundary conditions. Then the proposed upscaling method will be explained.
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2.1 Numerical simulation of a two-phase flow within a fibrous medium

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2.1.1 Physical problem and conservation laws

447 Two-phase flows with a moving interface are here addressed by solving two
448 coupled problems. The first one corresponds to the fluid problem and consists
449 in solving mass and momentum conservation equations on the computational
450 domain Ω (Fig.1). Both liquid and vapor phases are assumed to be newtonian
451 fluids and the flow incompressible. As the invading phase under consideration
452 shows a high viscosity and low velocity, a sufficiently low Reynolds number
453 can be assumed:
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$$Re = \frac{2\bar{r}\rho_L v_{in}}{\eta_L} \ll 1 \quad (9)$$

where ρ_L is the liquid density and \bar{r} the average fibre radius. Consequently, the convective and transient terms of Navier-Stokes' equations can be discarded. As a consequence, Stokes equations are here considered [37]. Let us consider that phase $i \in \{L, V\}$ occupies a domain $\Omega_i(t)$ at time t . The following problem is solved:

$$\left. \begin{aligned} \nabla \cdot \mathbf{v} &= 0 \\ \eta_i \Delta \mathbf{v} - \nabla p &= 0 \end{aligned} \right\} \text{ in } \Omega_i(t) \quad (10)$$

As an interface condition, no-slip is prescribed on the fibres.

Capillary effects are taken into account through Laplace's relationship already introduced in Eq.5 where $j \in \{LV, LS, SL\}$ (Fig.1). The contributions associated to the solid phase in Eq.5 vanish, as the fibres are supposed to be non-deformable. As a numerical consequence, the solid domain Ω_S is not meshed. Surface tension coefficients and viscosities are chosen to be consistent with experimental measurements [38] encountered in direct manufacturing processes of composite materials, and can be found in Table 1.

The model requires to locate the phases and the liquid-vapor interface Γ_{LV} in order to compute capillary terms or to apply the proper fluid properties. The interface is here modeled implicitly with a level-set method. The method leans on a scalar field ϕ that describes the signed distance between each point of the computational domain and the liquid-vapor interface [39]. Therefore the zero iso-value of the field corresponds to the liquid-vapor interface. **The whole field is then convected in the fluid velocity field \mathbf{v} to describe the moving interface [37]:**

$$\frac{\partial \phi}{\partial t} + \mathbf{v} \cdot \nabla \phi = 0 \quad \text{in } \Omega \quad (11)$$

with $\Omega = \Omega_L \cup \Omega_V$. **The resolution of Eq.11 requires both initial and boundary conditions. The initial level-set field corresponds to a plane liquid/vapor**

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507 interface, close to the inlet boundary. A boundary condition, usually on the
508 inlet boundary, is prescribed as a non-zero constant value for which the sign
509 indicates which phase enters the volume. Finally, to ensure that the field ϕ re-
510 mains a distance function throughout the computation, a reinitialisation step
511 is performed [40, 41].
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516 **2.1.2 Numerical strategy for solving the physical problem**

518 The problem described in the previous section (Eqs. 10,11) is solved with a
519 finite element approach through an in-house implementation in Z-set software¹.
520 The validity of the numerical strategy has been proved in various contributions
521 [37, 42–48]. The fluid problem is solved using linear approximations for both
522 velocity and pressure fields, associated with an ASGS strategy [49, 50]. The
523 implementation of capillary conditions at interfaces will not be detailed here
524 but further explanations can be found in [43]. Then, the level-set field is also
525 approximated by linear functions and its convection (Eq.11) is stabilised by a
526 SUPG method [51]. Both fluid and level-set problems share the same mesh and
527 are weakly coupled. An exemple of simulation within a fibrous microstructure
528 is represented in Fig.2.
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538 **2.1.3 Generation of fibrous microstructures**

540 The porous medium under consideration is made of long carbon fibres. As a
541 consequence, it is common to work within the plane that is tranverse to the
542 fibre axis [46]. This leads us to consider a 2D flow around a set of disks.
543 Fibrous microstructures have thus been randomly generated, from an input
544 value of fibre volume ratio V_f , and through an algorithm detailed in a previous
545 contribution [46]. In that paper, it was shown that the generated microstruc-
546 tures are statistically representative of real fibrous structures with respect
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551 ¹<http://www.zset-software.com/>
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to both mechanical response and geometrical considerations. In that sense, the microstructures can be considered as Statistical Representative Volume Elements (SRVE) [52]. The geometries are thus able to grasp the inherent randomness of the medium. To our knowledge, studying the impregnation of fibrous media from such volumes through transient two-phase flow simulations is a novelty, as similar studies are generally based on idealised representations of fibrous structures, using unit cells for instance.

In [46], a (S)RVE size has been determined for permeability considering steady flow simulations. It has been remarked that RVE is met for a size L such that $L/\bar{r} \approx 80$. However, for significantly lower value of L/\bar{r} , the results have been found to yield permeabilities very close to the asymptotic value. As a result, the RVE size has been set at 50 as a satisfactory trade-off between the statistical representativity and the computation cost. Fibre density will be kept here at 50% to consider an intermediate value.

2.2 Upscaling methods

2.2.1 Saturation

Saturation S_L is defined here as the proportion of liquid volume $|\Omega_L|$ over the overall poral volume $|\Omega|$:

$$S_L = \frac{|\Omega_L|}{|\Omega|} \quad (12)$$

It is thus defined at the volume scale and gives a global characterisation of the flow. Its temporal evolution translates the overall dynamics of the flow. It especially depends on the flow control that is prescribed through inlet/outlet boundaries of the volume (Fig.3). The imbibition of the fibrous structure is mainly driven by the boundary conditions prescribed at the inlet/outlet boundaries. Depending on whether a pressure drop or a flow rate is prescribed, the dynamics of impregnation can be significantly different. Consequently, as

discussed in the next paragraph, the type of flow control influences directly the time evolution of S_L .

When the same constant flow rate is prescribed at the inlet/outlet boundaries, the time evolution of S_L is first linear as the incompressible fluid is forced to travel the same distance at any time (Fig.3). Then, saturation converges towards an asymptotic value S_L^{max} as the flow reaches steadiness. On the contrary, if a pressure drop between the inlet and outlet boundaries is prescribed, the time evolution of S_L is non-linear and a clear transition between flow regimes is complex to identify. As the liquid fills the pore space, the overall volume viscosity increases and the fluid displacement induced by the pressure drop becomes increasingly smaller. Consequently, the average fluid velocity may drop by several orders magnitude between the beginning and the end of the simulation. This may alter the flow behaviour over time, particularly the competition between viscous and capillary effects which is represented through the capillary number Ca [53] (Eq.1).

In infusion-based manufacturing processes for composite materials, a pressure drop is imposed at the industrial part scale. At the local scale under consideration, this would lead to prescribe different pressure values on opposite sides of the domain. However, the aim of this study is to characterise the upscaling of local flows. For this purpose, it seems necessary to have a strong control on the flow regime throughout the simulation: a flow rate control will be prescribed on the volume in the rest of the study. A wall condition (i.e. $\mathbf{v} = \mathbf{0}$) is applied on the boundaries that are parallel to the imposed flow. Note that, although the microstructure is periodic, no periodic boundary condition has been used here. Indeed, in the case of a two-phase flow a periodic boundary condition should ensure the periodicity of the velocity, but should also guarantee that the same phase is considered on the corresponding nodes of both boundaries.

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Since the mechanical response is supposed to be independent of such boundary conditions as soon as the geometry can be regarded as a RVE, which is the case here [46], wall conditions have been considered throughout this study.

The slope of the $S_L = S_L(t)$ curve, as well as S_L^{max} , provide a global yet rough description of the flow. The characterisation can be carried further by giving a more localised definition. Let us consider a section A of surface $|A|$ whose normal vector is along the imposed flow-rate (Fig.4). At a given time t , this section contains a liquid surface $|A_L|$. This allows to define a local saturation $s_L(A)$ associated with section A as:

$$s_L(A) = \frac{|A_L|}{|A|} \quad (13)$$

This provides a time characterisation of the flow that also depends on the position. The $s_L(A)$ values are expected to be zero as long as the flow does not reach the section under consideration. Then a transition until a maximum value $s_L^{max}(A)$ should occur [18]. This value allows to characterise the steady flow that sets in section A . The transition time between the transient and steady states thus give an information about the local dynamics of the flow. However, it is more suitable to deal with a space variable as retrieving a physical time from numerical simulation of two-phase flow can be difficult [43, 54]. In the literature, local saturation is expressed as a function of the position considering that each section reaches full saturation. This assumption does not hold here as the void content at final state is not necessarily negligible. This leads to introduce the following quantity R :

$$R(t; A) = \frac{s_L(t; A)}{s_L^{max}(A)} \quad (14)$$

691 It describes, at time t and for a given section A , how reached the steady
 692 state is. As a consequence, $R = 0$ indicates that the fluid has not reached the
 693 section A yet. Inversely, the value $R = 1$ means that the flow is steady. For
 694 any value between 0 and 1, the flow is considered as transient. The value of
 695 R can be represented at a given time t as a function of the section position.
 696 Assuming an imbibition from the left side to the right one as depicted in
 700 Fig.4, $R(A; t)$ is expected to go from 1 to 0. The transition zone between
 702 those asymptotic values is associated to a *saturation length* ℓ_s corresponding
 704 to partially saturated zone. As the poral structure is isotropic, we expect this
 705 saturation length to stabilise towards a constant value. Even if the volume
 706 does not reach the rigorous RVE size, ℓ_s should be compared to the domain
 707 characteristic length so as to give first conclusions about the separation of
 709 scales.

713 **2.2.2 Resulting capillary pressure**

714 The resulting capillary pressure is here computed at the interface level from
 715 Eqs. 7 and 8. The methods to evaluate these quantity in practice are now
 716 detailed. An expression for the macroscopic capillary pressure is first obtained
 717 from the average pressure jump at the interface (Eq.7). To do so, elements of
 718 the mesh that are cut by the interface (i.e. the zero iso-value of the ϕ field)
 719 are scanned. For each one, the difference of mean pressure on either side of
 720 the interface is computed. This gives a distribution of local capillary pressure
 721 from which the median value is taken. This quantity will be referred to as
 722 *pressure jump* capillary pressure and denoted as P_p^c .

723 A second possibility to compute the capillary pressure is to consider the
 724 average mean curvature (Eq.8). Such an approach is usually avoided as it
 725 requires a double derivative computation which is numerically sensitive. As the
 726

liquid-vapor interface is generally non-continuous and fragmented, one must first isolate each continuous piece of Γ_{LV} . Considering the linear approximation of the fields, every interface piece corresponds to a small set of continuous segments which have first to be smoothed so that the mean curvature can be computed.

As a method suitable for small dataset while providing a good smoothing of the curves, a Gaussian Process Regression (GPR) technique is here selected [46, 55, 56]. Here, each continuous piece of interface is seen as a parametric curve. For each one, a GPR is carried out with the arc length as input and each cartesian coordinates as outputs. Then the mean curvature can be easily computed for each continuous piece of the interface. This yields a distribution of mean curvature from which the median value is taken to retrieve a representative scalar quantity. This will be referred to as *mean curvature capillary pressure* and denoted as P_C^c . Despite the efficiency of the method, a considerable number of GPRs is required leading to significant computational costs.

Those methods for computing the interfacial capillary pressure are validated with the following test case: a 2D bubble with a unitary radius (i.e. a unitary curvature) is placed in a square domain (Fig.5). As a unitary surface tension coefficient is chosen, the capillary pressure is expected to be equal to one. In addition, a very low pressure drop is prescribed on the volume to make the bubble move slightly on the fixed mesh (Fig.5). As the pressure drop has a low intensity, no geometrical change of the bubble is observed and a simple translation occurs. This aims at assessing the robustness of the methods throughout the simulation.

The results of both methods are compared in Fig.6 for a given mesh. The relative error with respect to the expected unitary capillary pressure is plotted.

783 As for all the presented graphs, time t is normalised by the final time t_f . Even
 784 though both curves show a certain variability, it lies under 1% in absolute
 785 value. Furthermore, the median error for both capillary pressures gives very
 786 satisfactory results. The mesh convergence has also been studied as represented
 787 in Fig.7. As expected, the finer the mesh, the smaller the error. It should be
 788 remarked that mean curvature capillary pressure gives more precise results for
 789 a given mesh. The technique is especially very performing for coarse meshes.
 790 As regards the pressure jump capillary pressure, the precision of the method is
 791 enhanced by the enrichment of the elements cut by interface [43, 57]. Finally,
 792 both methods quickly converge towards the expected theoretical value. This
 793 gives us confidence in both of the proposed approaches.

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804 **2.2.3 Statistical description of the flow front**

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806 A new method to define the flow front position in the homogenised equivalent
 807 representation is now detailed. The main idea is to assume that the tran-
 808 sient behaviour is only localised in a band, the characteristic length of which
 809 corresponds to the flow front width, as depicted in Fig.8. Outside this area,
 810 the behaviour is assumed to be steady. Indeed, a static equilibrium between
 811 phases is supposed to be met upstream while the fluid have not reached the
 812 downstream area yet. Inside \mathcal{F} (Fig.8), the liquid-vapor interface is generally
 813 non-continuous. The presented approach considers the position of the inter-
 814 face within \mathcal{F} through a statistical description. Considering our numerical
 815 approach, the interface corresponds to a set of segments for which endpoints
 816 position are denoted as $\mathbf{x}_i^{\mathcal{F}} = (x_i^{\mathcal{F}}, y_i^{\mathcal{F}})$. The coordinate that follows the flow
 817 direction is considered as a realisation of a random variable. In the example
 818 described in Fig.8, this corresponds to the abscissa of the points that compose
 819 the interface and it is denoted as $I_{x^{\mathcal{F}}}$. This random variable is expected to

follow a Gaussian law, as the interface is mainly centred around a certain position and its density then decays symmetrically from it.

This method requires the identification of the flow front which can be difficult in practice. Here, the domain is divided into rectangles in the direction of flow (Fig.9). For each rectangle, the most downstream point of the interface is fetched (\mathbf{x}^* for the dark blue rectangle in Fig.9) and its associated piece of interface is retrieved (the green piece of interface in Fig.9). This method allows a good reconstruction of the interface even if some errors of attribution may occur (Fig.10).

3 Results

Results obtained through the methods detailed previously are now presented. Transient two-phase flow simulations have been carried out in a numerically generated fibrous microstructure with a fibre density V_f equal to 50% and a capillary number Ca equal to 10^{-3} . **This value is frequently chosen in the composite materials community as it has been shown to minimise the vapor content at final state, optimising therefore the impregnation quality [58, 59].**

3.1 Global and local saturations

The global saturation S_L is first considered. An example of temporal evolution for S_L has been represented in Fig.11. As noticed previously, such a curve shows two regimes: a linear transient phase and a subsequent convergence towards a two-phase equilibrium as the liquid has filled-in the volume. Despite the simplicity of this behaviour, several upscaling descriptors with physical meaning can be extracted. The slope of the first phase can be computed to characterise the global dynamics of the flow. Then, the time to reach stability may be compared between different microstructures with the same fibre

875 density and simulation parameters. At last, the asymptotic saturation value
 876 S_L^{max} corresponds to the residual proportion of vapor phase which is usually
 877 referred to as a void content in the composite materials community. Due to the
 878 flow incompressibility hypothesis, S_L^{max} may overestimate the experimentally
 879 observed values as density inside bubbles cannot change. These three descrip-
 880 tors (i.e. saturation curve slope, filling time and maximum saturation) will be
 881 studied more precisely through a statistical further study.

886 Saturation defined at section level is now under consideration. It can be first
 887 represented as a function of time for different sections of a same geometry. The
 888 observed behaviour follows the expected sigmoid as represented in Fig.12 for
 889 three given sections. As noticed previously, it is suitable to transpose the curve
 890 into the spatial domain to retrieve a saturation length. This has been achieved
 891 by considering the ratio R introduced in Section 2.2.1 as depicted in Fig.13 at
 892 three given times. From the transition width of these curves, saturation length
 893 ℓ_s can be derived at any given time. As a consequence, it can be considered as
 894 time-dependent as depicted in Fig.14. To recover a representative scalar quan-
 895 tity, saturation length is considered to be globally stable around a finite value
 896 ℓ_s^* , represented by a dashed line in Fig.14. In the case under consideration, this
 897 saturation length value is found to be around $7.6\bar{r}$. This means that the RVE
 898 size is sufficient here for the flow to settle in steady regime.

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911 **3.2 Resulting capillary pressure**

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913 The resulting capillary pressure is computed throughout the simulation dura-
 914 tion. Both methods that have been presented previously are considered. The
 915 temporal evolution of P_p^c and P_C^c is represented in Fig.15.

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917 It can be observed that both behaviours are in very close agreement. The
 918 curves eventually converge towards very similar asymptotic values. These will
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be denoted by a star in exponent (i.e. P_p^{c*} and P_C^{c*}). We have here: 921

$$P_p^{c*} \approx P_C^{c*} = 12.7 \text{ kPa} \quad (15) \quad \begin{array}{l} 922 \\ 923 \\ 924 \\ 925 \\ 926 \\ 927 \end{array}$$

The time to reach stability can be interpreted as the time necessary to loose 928
memory of the initialisation state. A certain amount of time is therefore 929
required to reach a physically consistent state. This is the behaviour of a 930
statistically isotropic porous medium [46], however stability might not be 931
met for more complex poral structure materials [44]. Comparing Fig.11 and 932
Fig.15, it must be noticed that the capillary pressures P_p^c and P_C^c converge 933
while the global saturation is not stable yet. This shows that interface-defined 934
capillary pressure becomes here independent of both time and saturation. 935
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The results are in agreement with other recent works in which capillary 941
pressure defined at the interface level tends to converge after a certain time. 942
This reinforces the idea that capillary pressure, as defined here, can be con- 943
sidered as a function of the geometry and the interface properties only. Based 944
on such a definition, it can be regarded as independent on the saturation. 945
Consequently, considering an interfacial capillary pressure avoids the use of 946
saturation-capillary pressure relationship which limits have been highlighted 947
previously. 948
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3.3 Statistical description of the flow front 959

A methodology to describe the flow front in terms of probability of presence 960
has been described in Section 2.2.3. An example of distribution of flow front 961
at a given time t is represented in Fig.16. The distribution can be modeled by 962
a Gaussian law $\mathcal{N}(\mu, \sigma; t)$ as justified in Section 2.2.3. However, this trend 963
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967 is not necessarily clear in practice. Indeed, identifying precisely the flow front
968 can be difficult [60, 61]. Attribution errors such as depicted in Fig.10 may lead
969 to alter the observed distribution. Yet, such a modeling will be kept as a first
970 approach.
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973 The temporal evolution of the flow front distribution is represented in Fig.17.
974 The mean value $\mu(t)$ shows a linear trend over time. The standard deviation
975 $\sigma(t)$ starts to increase before being roughly stable around a value σ^* . From
976 Fig.17, this asymptotic value is estimated at $\sigma^* = 5.6\bar{r}$.
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982 4 Discussion

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985 Results from the proposed upscaling procedure have been presented in the
986 previous section. These have now to be compared to experimental observations
987 or to other numerical studies.
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991 4.1 Saturation

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Analogous curves to those represented in Fig.11 can be found in the litera-
ture for similar boundary conditions [17, 18]. Even for different geometries
and scales, as long as a flow rate is prescribed, the saturation increases lin-
early until reaching a plateau. Asymptotic saturation value S_L^{max} should also
be compared to void content obtained in other study for similar Ca . However,
most of the contributions on fibrous media set at an intermediate mesoscopic
scale: a dual-scale medium is thus considered as the liquid phase flows within
and around yarns (i.e. bundle of fibres) [16, 17, 58, 62, 63]. This work focuses
more specifically on the fibre scale: only microvoids are studied here.

The fraction of residual vapor phase retrieved here is significantly higher than
values commonly found in the literature. These generally lie between 1% and
10% for similar capillary numbers. It should be noticed that fibre fraction

within yarns can reach really high values, around 75% [44]. For such a compact- 1013
 ity, the fibrous arrangement tends towards a regular hexagonal packing. This 1014
 entails an overall regular advancement of the flow front and thus a lower final 1015
 void content. Moreover, further mechanisms such as air compressibility and 1016
 dissolution [60] tend also to diminish the residual proportion of vapor phase. 1017
 As regards local saturation, making a comparison with other studies can be 1018
 complex. Indeed, most of them are located at a mesoscale involving a much 1019
 larger saturation length. Here, the computed saturation length is around 25 1020
 μm for a mean fibre radius of $3.5 \mu\text{m}$. Considering the directly upper scale 1021
 on the order few millimeters [44], the scales seem to be well separated. This 1022
 means that at upper scales, the width of the unsaturated zone present at fi- 1023
 bre scale can be neglected. In other terms, in 2D, the moving interface within 1024
 the yarns can be wisely modeled by a 1D front in the equivalent homogeneous 1025
 medium as it can be done with a level-set method. 1026
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4.2 Capillary pressure

A consistency between both methods to assess a resulting capillary pressure has 1039
 been shown previously. Close asymptotic values are thus obtained and should 1040
 be now compared to experimental results. Capillary pressure assessment in fi- 1041
 brous media has been a concern of the composite materials community over 1042
 the past twenty years [7, 36, 63–65]. However, a huge dispersion of the results 1043
 can be observed in practice as depicted in Fig.15. Therefore, the comparison 1044
 of our results with those found in the literature can be a difficult task, espe- 1045
 cially because fibre volume ratio or the geometries can be different. However, 1046
 the orders of magnitude remain consistent. Moreover, the mean value of the 1047
 capillary pressure results found in the literature is 12.2 kPa. This value is very 1048
 close to the asymptotic capillary pressure retrieved in this study (Eq.15). In 1049
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1059 addition, it seems appropriate to consider some of the presented experimental
 1060 results as relevant bounds for capillary pressure. Considering Fig.15, results
 1061 from [64] represents a relevant lower bound while Pucci *et al.* measurements
 1062 from [64] represents a relevant lower bound while Pucci *et al.* measurements
 1063 [7] give a satisfactory upper bound.

1065 Analytical models have been also established to assess capillary pressure within
 1066 fibrous media [66–71]. The macroscopic contribution of capillary pressure is
 1067 then expressed as:

$$1070 \quad P_c = \frac{\gamma_{SV} - \gamma_{SL}}{r} \frac{V_f}{1 - V_f} \quad (16)$$

1071 where r is the fibre radius. For our material data and replacing r by the
 1072 mean fibre radius \bar{r} , this equation (Eq.16) estimates the resulting capillary
 1073 pressure at 8.2 kPa as represented in Fig.15. Even if this value is lower than
 1074 ours, it provides a satisfactory estimation. Indeed, we are considering here a
 1075 single random microstructure: a further statistical assessment of the capillary
 1076 pressure should be performed. In addition, the stochasticity of the geometry
 1077 under consideration (i.e. radius randomness, fibre position randomness,...) may
 1078 alter the expression of Eq.16.

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1088 **4.3 Statistical description of the flow front**

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1091 In Section 3.3, the flow front distribution has been characterised by a Gaussian
 1092 law. The advancement of distribution mean value has been shown to be linear
 1093 over time for flow rate inlet control conditions. This is consistent with the
 1094 saturation curve represented in Fig.11. We can thus write:

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$$1097 \quad \mu(t) \propto S_L(t) \quad (17)$$

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1100 The standard deviation $\sigma(t)$ of the flow front distribution can be physically
 1101 interpreted as a bandwidth within which the transient behaviour is contained.

This is very close to the concept of saturation length that has been introduced previously. It should be remarked that both ℓ_s and σ^* have comparable values. Seeing these quantities as characteristic length for the transient behaviour, both approaches appear to be consistent. Once again, it can be concluded that the spread of the flow front can be neglected at upper scales. This may justify the use of deterministic approach at both mesoscale and macroscale. Moreover, this reaffirms the relevance of considering a sharp interface at upper scales. This conclusion directly depends on the kind of porous medium under consideration as well as the flow parameters such as the capillary number [25]. In a more general case, the tools presented here provide a detailed description of the flow and give a thorough upscaling procedure.

Finally, in the context of this work, results arising from saturation (Section 3.1) and from the consideration of a flow front distribution (Section 3.3) are in close agreement. As noticed previously, this latter technique requires the identification of the flow front which can be challenging in practice. As a result, it seems preferable to use saturation-based methods for similar porous media and flow settings.

4.4 SRVEs and statistical mechanical response

In Section 2.1.3, the microstructures under consideration have been qualified as Statistical Representative Volume Elements, following the results from a previous study [46] and the definition from [52]. Indeed, our geometries are randomly generated and have been found to provide both a mechanical and geometrical representativity. In other words, given the SRVE nature of the generated geometries, the mechanical response of a single microstructure will be representative of a whole family of other geometries generated with similar

1151 fibre ratio volume and with analogous flow conditions.

1152 To illustrate it, the response of six randomly generated volumes with V_f equal
1153 to 50% are presented in Fig.18 and Fig.19, for $Ca = 10^{-3}$. It can be seen that
1154 the responses are indeed very close, both in terms of saturation or capillary
1155 pressure, even if an intrinsic dispersion is naturally observed. Since the present
1156 work aims at demonstrating the basics of the stochastic upscaling methodol-
1157 ogy dedicated to transient flows in composites manufacturing, a single SRVE
1158 has been considered. Obviously, a more exhaustive study is requested to fur-
1159 ther investigate the statistical upscaled flows in the space of the physical and
1160 geometrical descriptors.
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1170 5 Conclusion

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1172 This work contributes to bridge the approaches developed by hydrogeology and
1173 composite materials communities in order to reach an upscaling method that
1174 is adapted to the impregnation of fibrous materials. From an in-depth anal-
1175 ysis of the methods encountered in literature, a re-examination of the usual
1176 upscaling descriptors has been performed, so that they can relevantly charac-
1177 terise the imbibition of fibrous materials.
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1181 From 2D SRVEs, flow simulations have been performed through a stabilised
1182 finite element method. Upscaling methods have been then identified from the
1183 developments of various scientific communities. Those have been adapted to
1184 the context of random fibrous media at microscale and further strategies have
1185 been proposed.
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1189 First, the notion of saturation, that usually describes the proportion of liquid
1190 within the poral space, has been considered both at volume and section scales.
1191 Their temporal and/or spatial evolution naturally leads to upscaling descrip-
1192 tors related to saturation dynamics or void content. Results are consistent and
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the some identified discrepancies with the literature has been justified. Local 1197
saturation allows to determine a saturation length within which the transient 1198
behaviour is supposed to be contained. This length represents around 15% of 1199
the domain size. This allows us to conclude that the scales are well separated 1200
as the domain encompasses the entire transient behaviour. At upper scales, 1201
the width of the unsaturated zone may be neglected for the standard compos- 1202
ite materials under consideration. 1203
Then two methods have been proposed to assess a resulting capillary pressure 1204
from the interface behaviour. Both approaches have been validated on a test 1205
case and show an excellent agreement. A convergence of the capillary pressure 1206
is observed over time. It is thus independent of the saturation and only de- 1207
pends on the interface properties and inlet flow control. This may avoid the 1208
use of cumbersome relationship between saturation and capillary pressure. Our 1209
values of capillary pressure have been then shown to be in accordance with 1210
other analytical and experimental results. 1211
A novelty of this approach is to describe the flow front through a statistical 1212
modelling. After identifying the position of the flow front, a presence distribu- 1213
tion of the flow front is retrieved. In a first approach, this can be considered 1214
as a Gaussian law whose parameters behaviour are consistent with our pro- 1215
posed approach. In the situation under consideration, the spread parameter 1216
of the distribution is significantly lower than the characteristic length of the 1217
upper scale. This again justifies deterministic modeling of the flow front at up- 1218
per scales, for fibrous materials in the context of direct manufacturing processes. 1219
However, in the case of larger anisotropic porous media, the distribution spread 1220
may not be negligible anymore and the proposed statistical characterisation 1221
may be particularly relevant. 1222
Finally, the proposed strategy allows a thorough upscaling of the microscopic 1223
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1243 behaviour while justifying or reappraising some of the usual methods found
1244 in the literature. Both capillary number and fibre volume ratio has been kept
1245 constant here. Further studies should consider them as input variables of a
1246 more comprehensive model in which the presented upscaling descriptors are
1247 the output. This will allow to build a dataset so as to perform a more com-
1248 plete statistical characterisation of the upscaling.

1253 This contribution focuses on the upscaling methods so as to retrieve a novel
1254 procedure that is suited for the impregnation of fibrous materials. The up-
1255 scaling descriptors that have been highlighted are mostly scalar quantities
1256 and provide a thorough macroscopic characterisation of the flow under con-
1257 sideration. In future contributions, the influence of the flow settings and pore
1258 structure (*i.e.* Ca and V_f) on those descriptors will be investigated in order to
1259 extract constitutive laws ruling the imbibition of fibrous structures.

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1722 **Statements and Declarations**

1723 The authors declare that no funds, grants, or other support were received dur-
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1725 or non-financial interests to disclose.
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γ_{SV} (N/mm)	γ_{SL} (N/mm)	γ_{LV} (N/mm)	η_V (Pa.s)	η_L (Pa.s)
54.7×10^{-3}	25.9×10^{-3}	50.8×10^{-3}	1.71×10^{-5}	2.76×10^{-3}

Table 1: Fluid properties chosen for the numerical simulations.

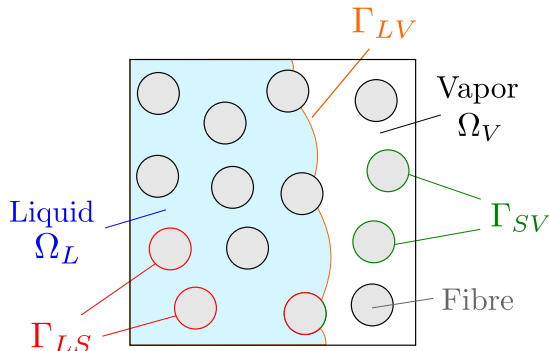


Figure 1: Imbibition in a fibrous medium: domains, boundaries and notations.

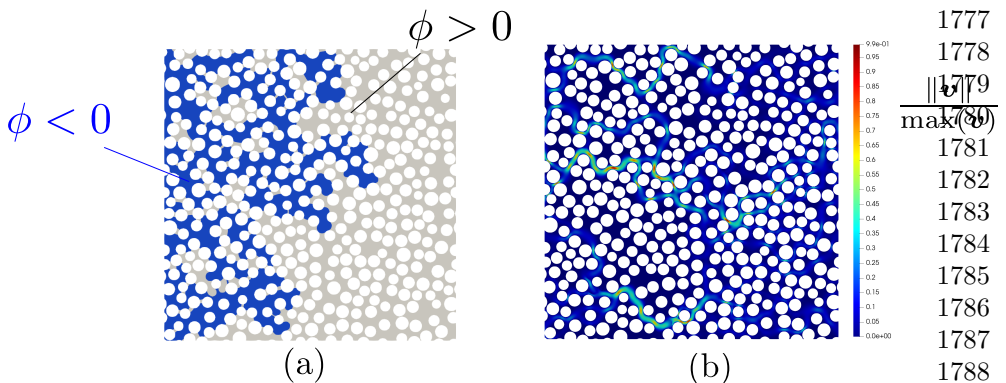
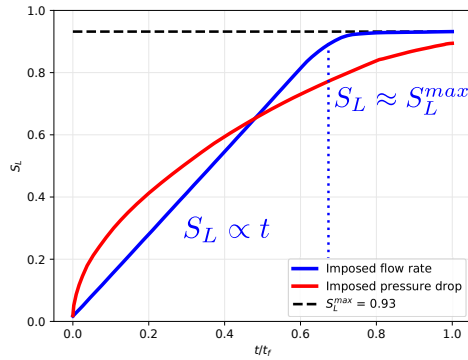


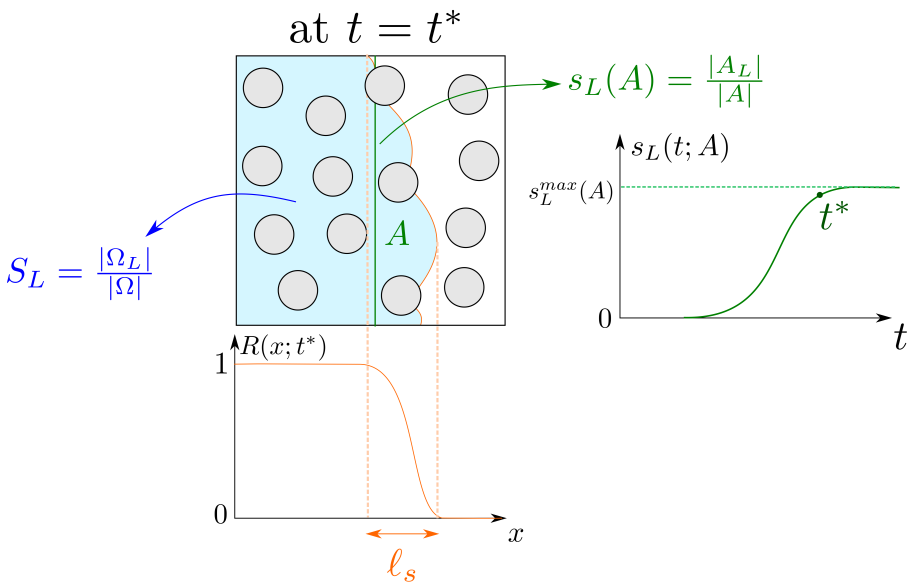
Figure 2: A simulation example of transient two-phase flow within a generated fibrous microstructure: (a) location of the phases (blue: liquid, grey: vapor), (b) normalised velocity magnitude.

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1810 **Figure 3:** Temporal evolution of global saturation S_L for different inlet
1811 boundary conditions.

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Figure 4: Notions of saturation and saturation length.

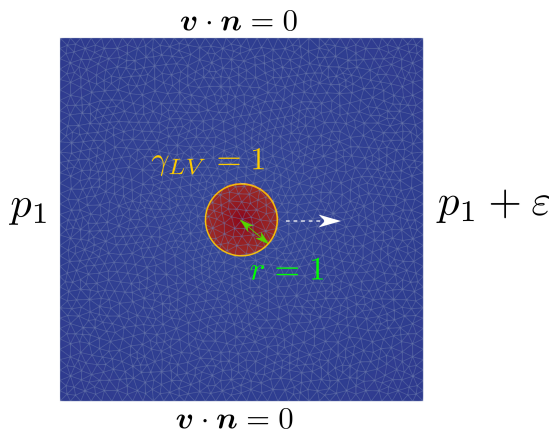


Figure 5: Test case for the validation of the resulting capillary pressure computation : parameters, boundary conditions and mesh (1655 nodes). A pressure of low intensity ε is prescribed.

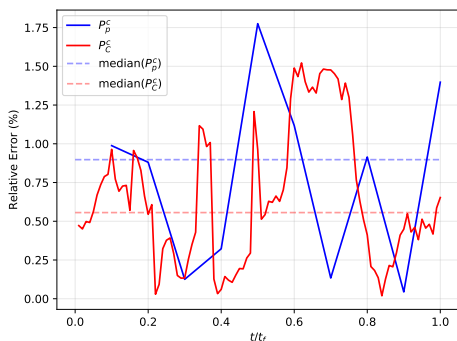


Figure 6: Relative error between reference value and the two methods to assess the resulting capillary pressure for a given mesh (1215 nodes).

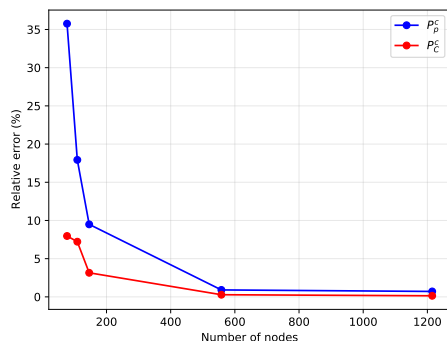


Figure 7: Mesh convergence for the two methods to assess the resulting capillary pressure.

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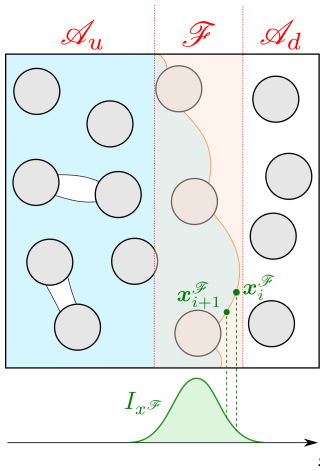
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1905 **Figure 8:** Statistical approach
1906 to describe the flow front.

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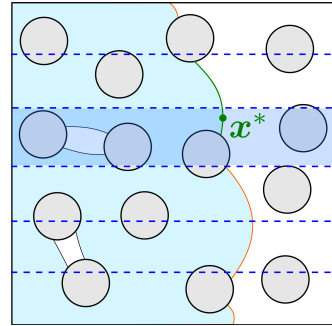
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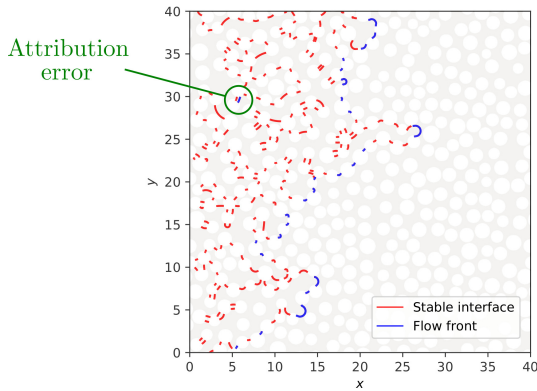
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1905 **Figure 9:** A method to identify
1906 the flow front.



1905 **Figure 10:** Example of flow front identification.

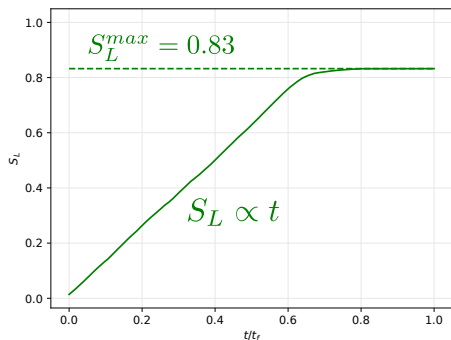


Figure 11: Temporal evolution of the global saturation.

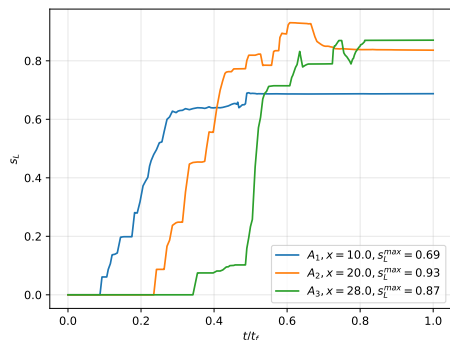


Figure 12: Temporal evolution of the saturation of three sections characterised by their abscissa x .

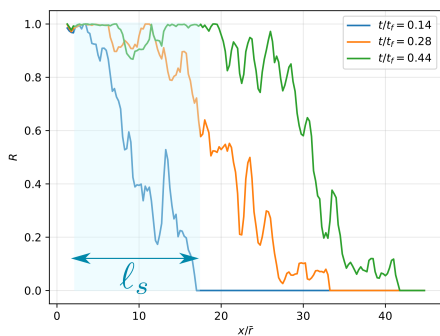


Figure 13: Spatial evolution of the ratio R for three given times.

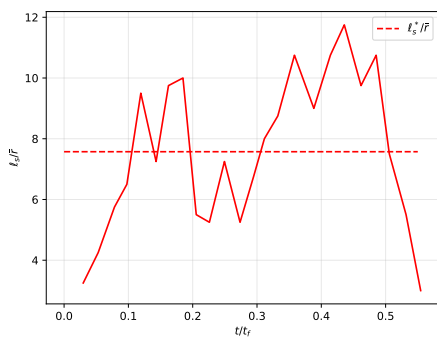


Figure 14: Temporal evolution of the saturation length normalised by the mean fibre radius.

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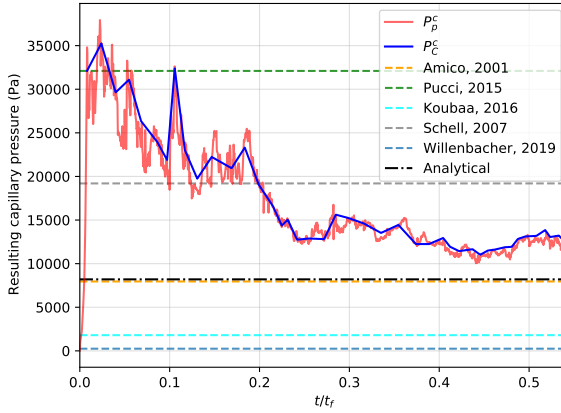


Figure 15: Temporal evolution of the resulting capillary pressure defined at the interface level: proposed methods and literature.

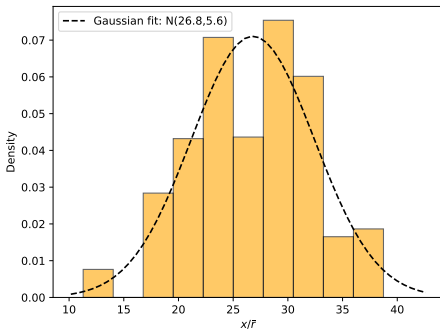


Figure 16: Distribution of flow front at $t/t_f = 0.73$.

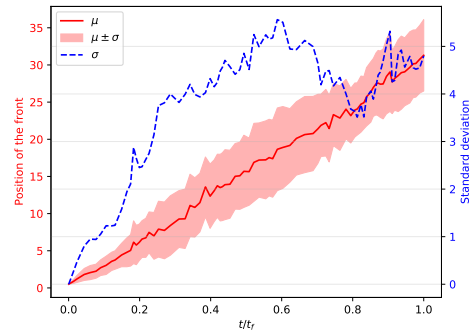


Figure 17: Distribution of flow front over time: mean value, dispersion and standard deviation.

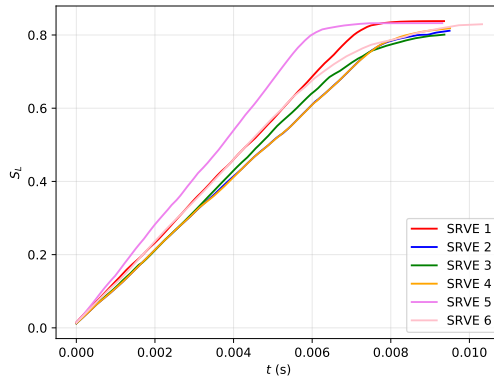


Figure 18: Time evolution of the global saturation for six randomly generated microstructures ($V_f = 50\%$, $Ca = 10^{-3}$).

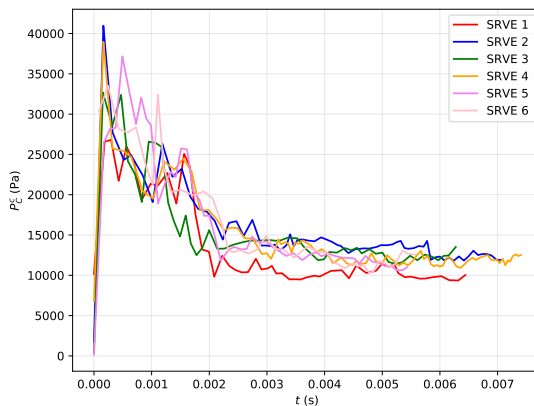


Figure 19: Time evolution of the resulting capillary pressure for six randomly generated microstructures ($V_f = 50\%$, $Ca = 10^{-3}$).

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